



# Design and Operational Experience of the Low Level RF Control at the S-DALINAC

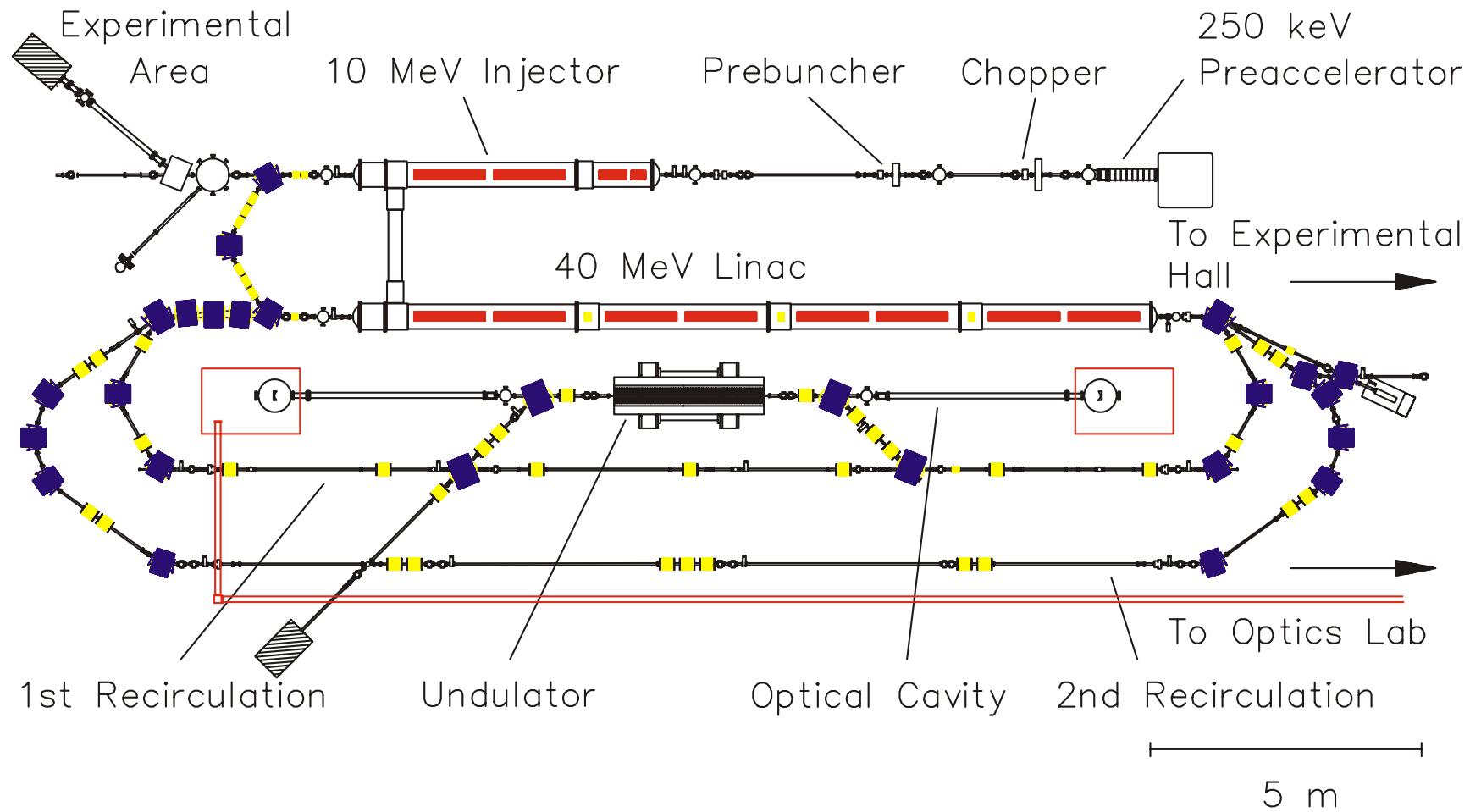
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- The Accelerator
- Experiments and Requirements
- RF Control
- Outlook



S-DALINAC

# S- DALINAC





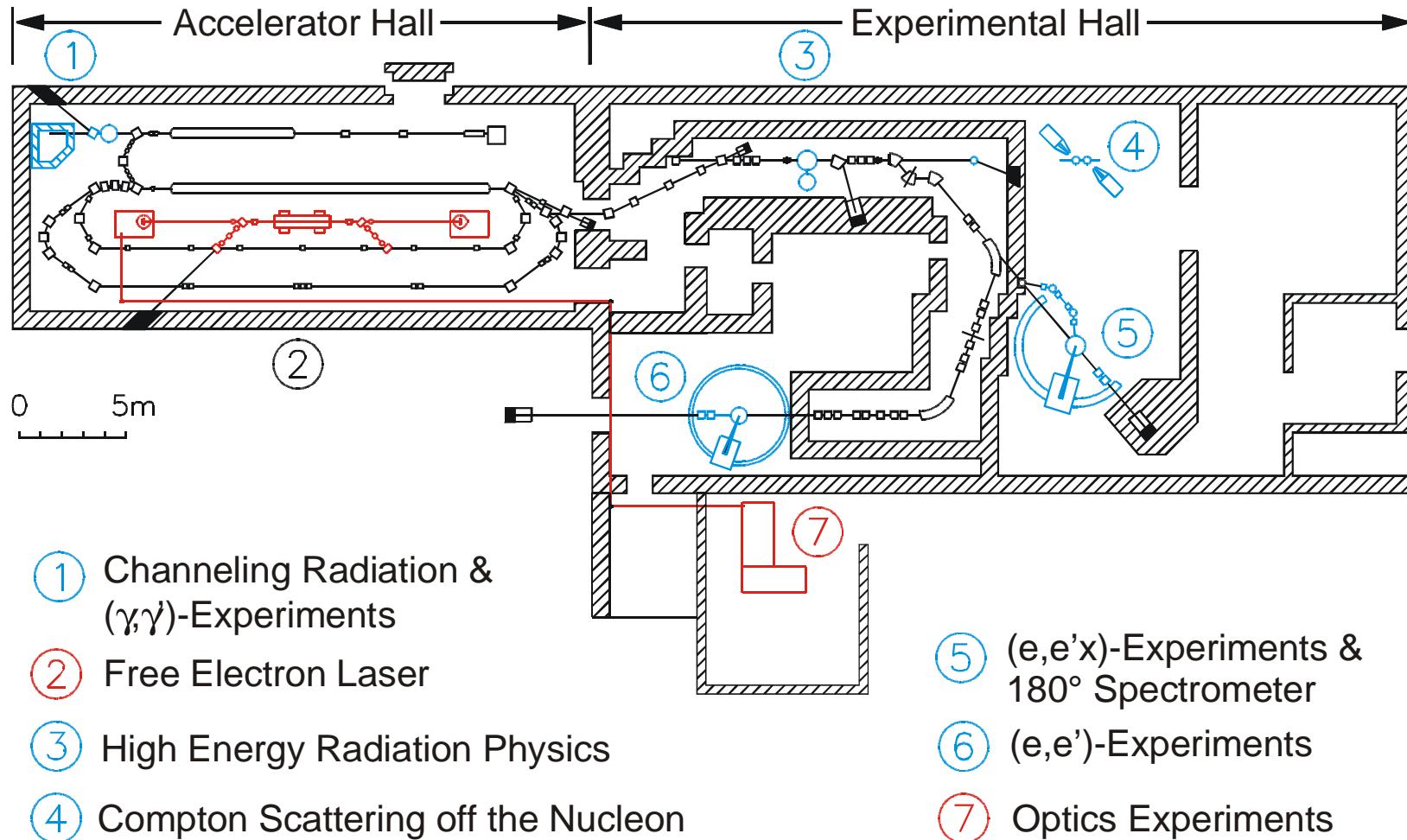
S-DALINAC

# S-DALINAC





# S-DALINAC and Experimental Facilities





# S-DALINAC Beam Parameters

Experiments	Energy (MeV)	Current ( $\mu\text{A}$ )	Mode	Time (h)
$(\gamma, \gamma')$	2.5 – 10	50	3 GHz, cw	6400
LEC, PXR	3 – 10	0.001 - 10	3 GHz, cw	2100
HEC, PXR	35 – 87	0.1	3 GHz, cw	800
$(e, e')$ , $(e, e'x)$	22 – 120 <sup>1)</sup>	5	3 GHz, cw	7800
FEL	30 – 38	2.7 A <sub>peak</sub>	10 MHz, cw	2900

1) Dutycycle 33%

$\Sigma$  20000

Resolution:  $\Delta E_{\text{FWHM}} = 50 \text{ keV} @ 85 \text{ MeV}$ ,  $\Delta E/E = \pm 3 \cdot 10^{-4}$



# Superconducting 20-Cell Cavity

Material:	Niobium (RRR=280)
Frequency:	3 GHz
Temperature:	2 K
Accelerating Field:	5 MV/m
$Q_0/Q_L$ :	$3 \cdot 10^9 / 3 \cdot 10^7$
$\Delta f/\Delta l$ :	500 Hz/ $\mu$ m



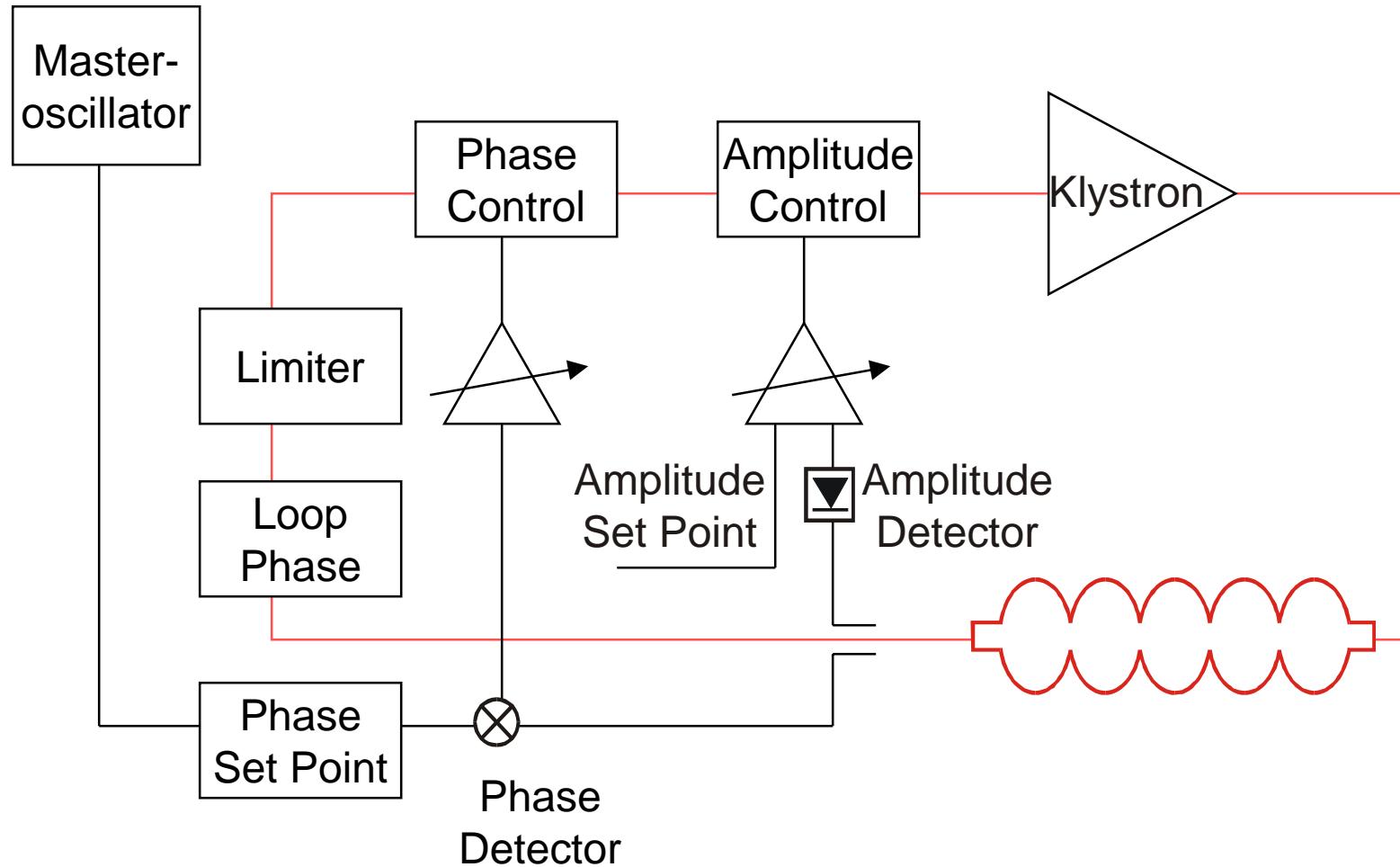
# Specification

- Energy spread:  $\Delta E/E = \pm 10^{-4}$  (fwhm)
- Concept: Isochronous acceleration  
on crest
- Contributions to energy spread
  - Bunch length:  $2^\circ \rightarrow 1.5 \cdot 10^{-4}$
  - Amplitude jitter:  $< 10^{-4}$  ( $\Delta l < 2 \text{ nm}$ )
  - Phase jitter:  $< \pm 0.5^\circ$  ( $\Delta l < 1.1 \text{ nm}$ )

RF Control required !!

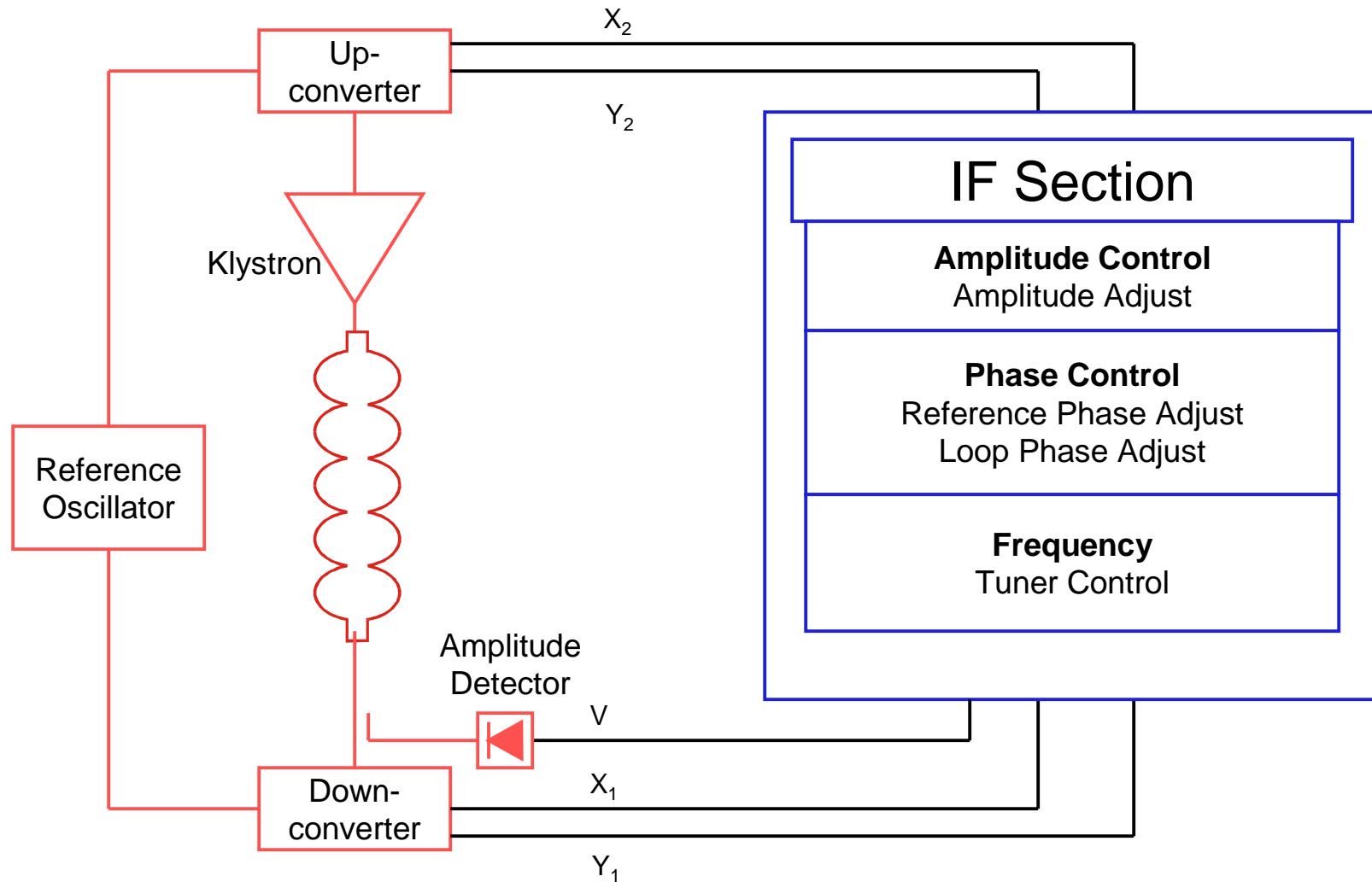


# Self Excited Loop



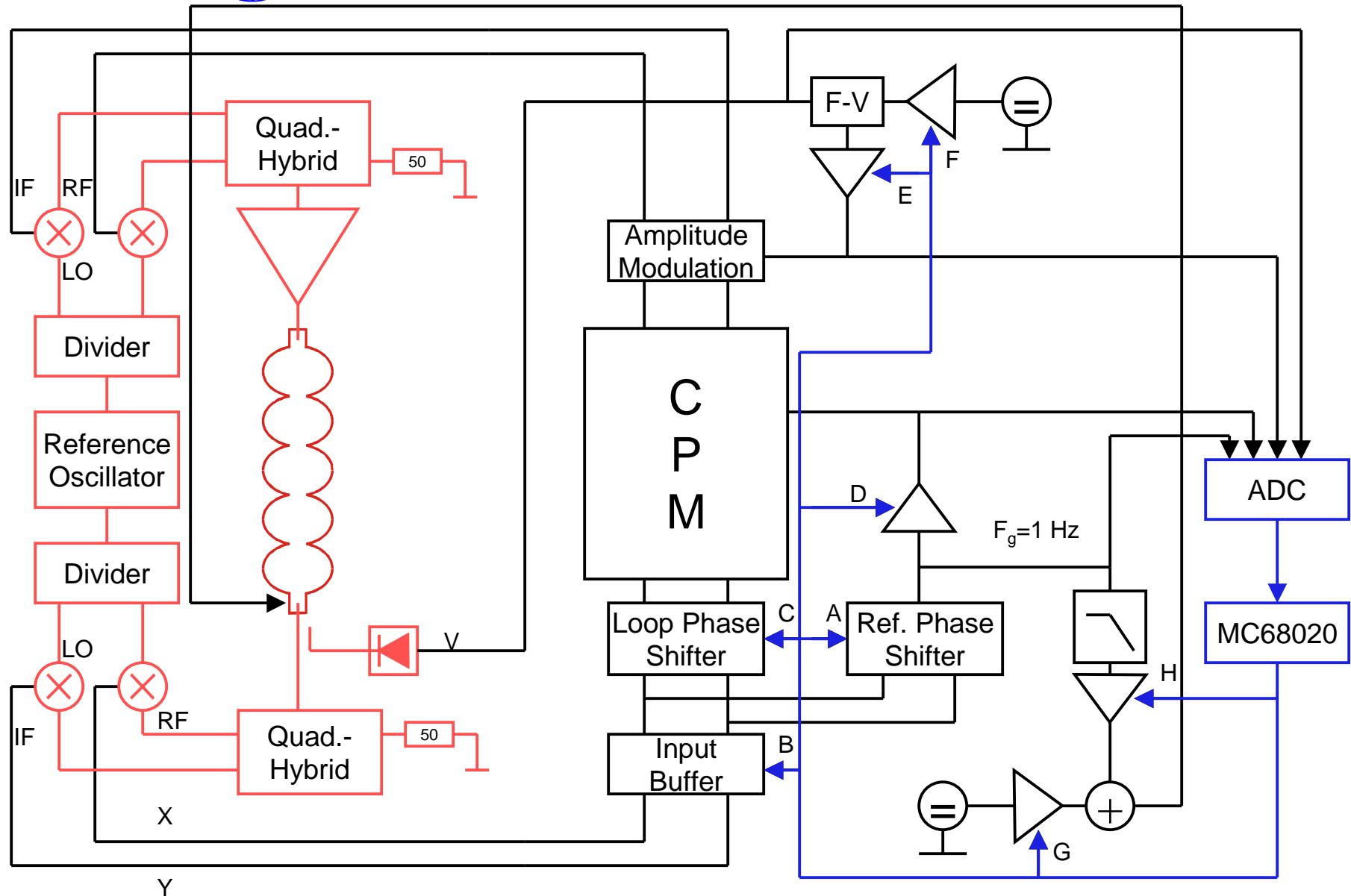


# Principle of the RF Control





S-DALINAC

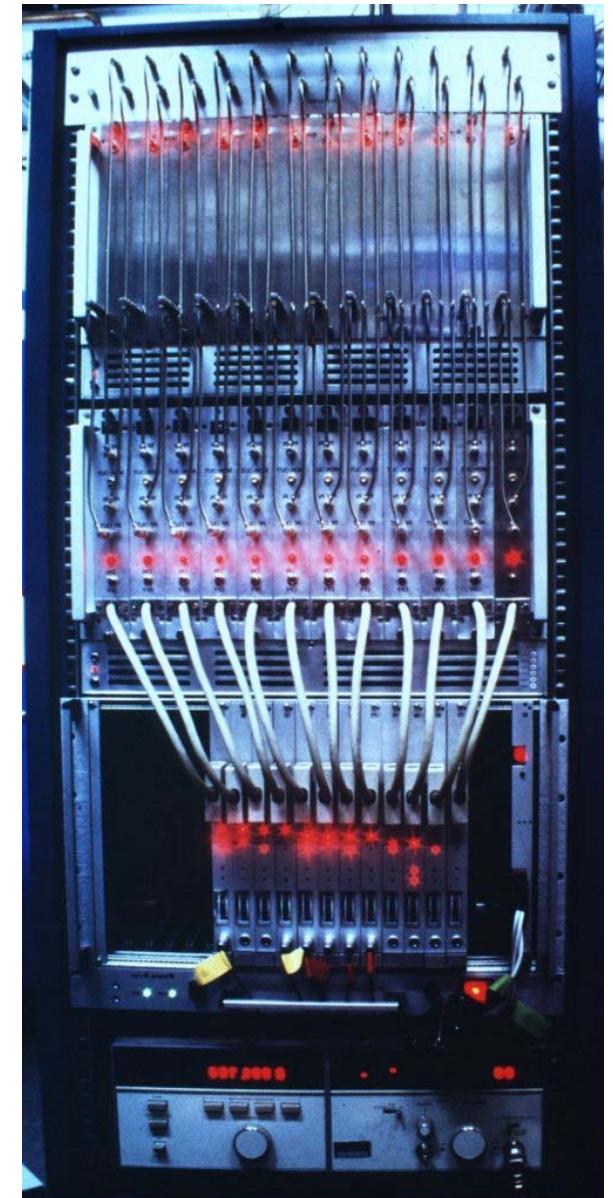




## Presently achieved

- Amplitude stability:  $\Delta E/E = 1 \cdot 10^{-3}$
- Phase jitter:  $\Delta \theta/\theta = \pm 0.3^\circ$

The phase control matches the specification,  
the amplitude control does not!





# Outlook

- Improvement on the RF side
  - Rebuild the up- and down converter with modern components
  - Implement a separated signal and control path for the amplitude signal
  - Temperature stabilization
- IF Section
  - Replace the existing analog control by a DSP based system
  - Reproduce the existing IF board in software
  - Implement features of a digital control, e.g. lookup tables for correcting nonlinear characteristics of components



# The Future RF Control ?

