# Jefferson Lab Alignment Group <br> Data Transmittal 

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Checked:
\# : A1925

## DETAILS:

data: M:lalign\DATA\Step2B\HALLA\MOLLER_DETECTOR\190605A M: \align\DATA\Step2B\HALLA\190523A

The Hall A Moeller experimental components were surveyed between May 23rd and June $5^{\text {th }}$, 2019. The ideal (designed) coordinates and angles are shown in the first table in meters and degrees relative to the JLab's CEBAF coordinate system.

The as-found table shows the current location in CEBAF system (meters) and the beam following system (BFS) in millimeters. The BFS data shows the as-found position as it follows the beam relative to the ideal position. In the BFS, a positive dx value is to the beam left looking downstream along beam from the ideal; a positive dy is along beam vertically from ideal (note the pitched data bfs xyz coordinates are along the pitched beamline - dy not truly vertical); A positive dz is downstream from ideal. The delta angle are shown in degrees and are the differences (found - ideal) from ideal. The distance from the standard Hall A target is shown [not PREX target].

Positive Yaw angles are counterclockwise about the $Y$ axis viewed from above, positive Pitch angles are clockwise about the X axis viewed from the left and positive Roll angles are clockwise about the Z axis looking downstream.

| CEBAF IDEAL DATA |  |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :---: |
|  | Accelerator coords METERS |  |  | ideal angles degrees |  |  |  |
|  | $x[\mathrm{~m}]$ | $y[\mathrm{~m}]$ | $\mathrm{z}[\mathrm{m}]$ | yaw | pitch | roll |  |
| MOLSOL | -43.57183 | 100.02200 | -379.19945 | 142.5000 | 0.0000 | 0.0000 |  |
| MOLTAR | -43.57183 | 100.02200 | -379.19945 | 142.5000 | 0.0000 | 0.0000 |  |
| MMA1H01 | -41.03793 | 100.02200 | -382.50167 | 142.5000 | 0.0000 | 0.0000 |  |
| MOLBOX | -39.25683 | 100.02200 | -384.82285 | 142.5000 | 0.0000 | 0.0000 |  |
| MOLDET | -39.02864 | 99.50960 | -385.12024 | 142.5000 | -7.3000 | 0.0000 |  |
| Hall A Target | -32.95843 | 100.02200 | -393.03108 | 142.5000 | 0.0000 | 0.0000 |  |


| FOUND DATA |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | found accelerator coords METERS |  |  |  | BFS [mm] |  |  | delta angles degrees |  |  |
|  | x[m] | y [m] | z[m] | to target[m] | dx | dy | dz | dYaw | dPitch | dRoll |
| MOLSOL | -43.57165 | 100.02200 | -379.19931 | -17.4344 | -0.23 | 0.00 | 0.00 | -0.0042 | -0.0049 | -0.0077 |
| MOLTAR | -43.57295 | 100.02180 | -379.19816 | -17.4361 | 0.10 | -0.20 | -1.70 | -0.0037 | -0.1942 | 0.2286 |
| MMA1H01 | -41.03806 | 100.02205 | -382.50139 | -13.2723 | -0.07 | 0.05 | -0.30 | -0.0062 | 0.0249 | -0.0026 |
| MOLDET | -39.01932 | 99.55340 | -385.13525 | -9.9595 | 1.74 | 45.66 | 11.88 | 0.1551 | -0.1569 | 0.2757 |

The PMT Detector was re-fiducialized on May $23^{\text {rd }}$. The $Z$ axis was defined by constructing a line through the upstream and downstream centers of the box. The upstream slot of the box was used to control roll ( Y axis). The origin was created by intersecting the Z axis and the plane constructed through the eight downstream aluminum tube faces. This was done in order to keep continuity between previous surveys. The table below shows the as-set locations of each of the paddle corner points as well as the upstream and downstream box centers.

The coordinates in the table below are reported in a beam following system (along the pitched line) relative to the MOLDET ideal. See picture below for naming convention.

|  | BFS (mm) |  |  |
| :--- | ---: | ---: | ---: |
|  | $\mathbf{X}$ | Y | Z |
| USBOX | 0.07 | 43.91 | -610.42 |
| DSBOX | 1.39 | 45.31 | -119.23 |
| PMTORIGIN | 1.74 | 45.68 | 11.87 |
| L1BOTBR | 27.63 | -108.16 | -625.19 |
| L2BOTBL | 63.06 | 95.73 | -629.00 |
| L3BOTBL | 63.32 | -5.11 | -640.74 |
| L4BOTBL | 63.19 | -109.46 | -655.25 |
| L4BOTBR | 44.31 | -109.31 | -656.15 |
| L3BOTBR | 44.50 | -5.16 | -640.99 |
| R1BOTBL | -22.89 | -111.40 | -624.71 |
| R2BOTBR | -62.83 | 89.49 | -626.80 |
| R3BOTBL | -45.91 | -5.42 | -642.44 |
| R3BOTBR | -63.76 | -5.46 | -642.94 |
| R4BOTBL | -44.08 | -111.29 | -654.81 |
| R4BOTBR | -62.45 | -111.43 | -655.30 |



