

Jefferson Lab Alignment Group

Data Transmittal

TO: D. Kashy **DATE:** 10 Sep 2015

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DETAILS: data: inspection\hallb\torus12g\150826A

The data below is from the Torus magnet survey of August 25th and 26th, 2015. The twelve found edge fiducial points were used to form a plane and a circle for the upstream and downstream positions. The origin is the coil case design zero as shown on drawing B00000-04-01-1101. The Z axis is determined by the central hub flanges, with the positive Z going from upstream to downstream. Positive X is perpendicular to the beam left from this line and positive Y is perpendicular in the vertical direction (not vertical to gravitiy).

Hub Line Data									
Local System (mm)				Cebaf Coordinate System					
	x[mm]	y[mm]	z[mm]		x[M]	y[M]	z[M]		
Design zero	0.00	0.00	0.00	Design zero	-80.60000	103.35526	-401.18852		
Upstream	-0.88	-4.07	457.83	Upstream	-80.59912	103.35119	-401.64635		
downstream	-0.52	0.66	2508.07	downstream	-80.59948	103.35592	-403.69659		
Found Angles	Yaw	Pitch							
	0.0101	0.1322							

In the local system, the found and ideal coordinates, plus their deltas are shown below. Additionally, a plane and circle were formed to the found data. Units are millimeters.

	Upstream Points Found		Ideals			Deltas			plane			
										fit	Planar	Radial
Coil	Х	У	Z	Х	У	Z	Х	У	Z	results	Error	Error
Α	0.43	3206.13	-499.99	0.04	3207.24	-507.04	0.39	-1.11	7.05	AUS	0.30	0.30
В	-2777.40	1602.66	-499.61	-2777.63	1603.47	-506.82	0.23	-0.81	7.21	BUS	-0.36	-0.23
С	-2778.45	-1603.77	-498.07	-2777.30	-1604.17	-506.91	-1.15	0.40	8.84	CUS	0.00	-0.10
D	0.25	-3208.87	-497.53	0.77	-3207.36	-507.04	-0.52	-1.51	9.51	DUS	0.40	0.36
Ε	2776.81	-1604.83	-499.43	2777.59	-1603.67	-507.00	-0.78	-1.16	7.57	EUS	-0.46	-0.28
F	2776.92	1602.40	-500.05	2777.63	1603.66	-507.05	-0.71	-1.27	7.00	FUS	0.10	-0.05
	Downstream Points Found			Ideals			Deltas					
	Downstrea	m Points Fo	ound		Ideals			Deltas		plane		
	Downstrea	m Points Fo	ound		Ideals			Deltas		plane fit	Planar	Radial
Coil	Downstrea x	m Points Fo	ound z	x	Ideals y	z	x	Deltas y	z	-	Planar Error	Radial Error
				x -0.03		z 878.24	x 0.65		z 6.52	fit		
Coil	x	у	z		у	_		у		fit results	Error	Error
Coil	x 0.62	y 4212.61	z 884.76	-0.03	y 4213.08	878.24	0.65	y -0.47	6.52	fit results ADS	Error 0.52	Error 0.05
Coil A B	x 0.62 -3649.70	y 4212.61 2104.63	z 884.76 885.10	-0.03 -3648.27	y 4213.08 2106.44	878.24 878.14	0.65	y -0.47 -1.81	6.52 6.96	fit results ADS BDS	0.52 -0.45	0.05 -0.03
Coil A B C	x 0.62 -3649.70 -3647.99	y 4212.61 2104.63 -2108.89	z 884.76 885.10 886.87	-0.03 -3648.27 -3648.72	y 4213.08 2106.44 -2106.07	878.24 878.14 878.17	0.65 -1.43 0.73	y -0.47 -1.81 -2.82	6.52 6.96 8.70	fit results ADS BDS CDS	0.52 -0.45 -0.16	0.05 -0.03 -0.05

The deltas above are relative to the coordinate system with a + z being too far downstream, +x being to the beam left from ideal, and +y above the ideal point. The planar errors are deltas from the determined plane. The planes normal angle is downstream and a positive value is the amount downstream. The radial error is the amount from the calculated circle center. A positive radial error means the point lies beyond the circle's edge.

The calculated circle centers are shown below, in the above referenced system.

Circle Centers						
Position	X	Υ	Z			
Upstream	-0.42	-1.35	-499.11			
Downstream	-0.20	-0.68	885.73			

The pitch and yaw rotation angles for the planes are shown below. Pitch is the rotation about the X axis. Yaw is the rotation about the Y axis. Positive follows the right hand rule. Units are degrees.

rotation angles for upstream							
Pitch	89.9790°						
Yaw	90.0093°						
Rotation Angles for Downstream							
Rx from Y	90.0202°						
Ry from Z 90.0089°							