## $\rightarrow$ Sceferan CLat $\rightarrow$ <br> Jefferson Lab Alignment Group Data Transmittal

TO: B. Miller, M. Mestayer
DATE: 15 Sep 2016
FROM: Chris Gould
DETAILS:

|  | DATE: 15 Sep 2016 |  |
| :--- | :---: | :---: |
| Checked: | \# : B1730 |  |
| M: 1 alignIDATA\Step2AIHALLBIRegion 21160914A |  |  |

Below are the results of the recent Region 2 detector alignment. Sectors 2 and 3 were positioned relative to the Torus magnet centerline with $\mathrm{Z}=0$ at the hall center. Values are in a beam following coordinate system where $+Y$ is up, $+X$ is to the beam left and $a+Z$ is downstream. In addition to the deltas between the measured values and the ideal coordinates, a plane was constructed through the measured fiducials to determine the rotation angles.

|  | Measured |  |  | Nominal |  |  | delta |  |  | mag |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | X | Y | Z | X | Y | Z | X | Y | Z |  |
| Sector 2 |  |  |  |  |  |  |  |  |  |  |
| R2_N1 | 180.577 | 248.67 | 2394.606 | 180.292 | 248.773 | 2394.546 | 0.286 | -0.103 | 0.06 | 0.31 |
| R2_N2 | 125.677 | 280.634 | 2394.756 | 125.299 | 280.523 | 2394.546 | 0.378 | 0.111 | 0.21 | 0.446 |
| R2_S2_2 | 2341.283 | 1578.757 | 1361.262 | 2340.974 | 1578.724 | 1361.507 | 0.309 | 0.033 | -0.246 | 0.396 |
| R2_S2_3 | 196.751 | 2816.605 | 1361.448 | 196.729 | 2816.703 | 1361.504 | 0.022 | -0.098 | -0.057 | 0.115 |
|  |  |  |  |  |  |  |  |  |  |  |
| Sector 3 |  |  |  |  |  |  |  |  |  |  |
| R2_N1 | -125.42 | 280.715 | 2394.635 | -125.466 | 280.848 | 2394.571 | 0.046 | -0.133 | 0.064 | 0.155 |
| R2_S3_1 | -196.676 | 2817.067 | 1361.11 | -196.816 | 2816.877 | 1361.154 | 0.139 | 0.19 | -0.044 | 0.239 |
| R2_S3_2 | -2341.21 | 1578.779 | 1360.996 | -2341.03 | 1578.836 | 1361.016 | -0.186 | -0.057 | -0.02 | 0.195 |

Sector 3 was measured then retracted and repositioned to check repeatability.

|  | Set 1 |  |  | Repeat |  |  | delta |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Repeatability | X | Y | Z | X | Y | Z | X | Y | Z |
| Sector3 |  |  |  |  |  |  |  |  |  |
| R2_N1 | -125.42 | 280.715 | 2394.635 | -125.475 | 280.659 | 2394.592 | -0.055 | -0.056 | -0.043 |
| R2_S3_1 | -196.676 | 2817.067 | 1361.11 | -196.709 | 2817.058 | 1361.159 | -0.033 | -0.009 | 0.049 |
| R2_S3_2 | -2341.21 | 1578.779 | 1360.996 | -2341.23 | 1578.81 | 1360.927 | -0.016 | 0.031 | -0.069 |

Rotation Angles.

|  | Rotation angles |  |  |
| :--- | ---: | ---: | ---: |
|  | Rx from Y | Ry from Z | Rz from X |
| Sector 2 | -111.841 | -166.971 | -120.000 |
| Sector 3 | -111.850 | 166.961 | -59.992 |

