#  <br>  <br> <br> Jefferson Lab Alignment Group <br> <br> Jefferson Lab Alignment Group <br> Data Transmittal 

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Checked: TPS III
\# : B1848

## DETAILS:

The Hall B target and beamline were surveyed January $11^{\text {th }}$, 2018. From the previous survey, (memo B1829 November $17^{\text {th }}$, 2017) the target was found to be 3.45 millimeters beam left, 0.42 millimeters below design (ideal) beamline and 19.4 millimeters upstream. The reason the target was not aligned closer was due to mechanical limitations of the cart / rails, plus not wanting to risk a collision of the scattering chamber and the inner detectors.

A decision was made (by S. Stepanyan and B. Miller) to move the target approximately 2 mm to the beam right. On January 9th, 2018, the target was offset in the x coordinate by 2.3 mm beam right and resulted in y coordinate being 0.2 mm higher than before. After aligning on the $11^{\text {th }}$ of January, the target is now at the following location from ideal:

| Component | As-Found BFS [mm] |  |  | As-Found Angular [degrees] |  |  |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: |
|  | $\mathbf{x [ m m}]$ | $\mathbf{y [ m m}]$ | $\mathbf{z}[\mathrm{mm}]$ | yaw[deg] | pitch[deg] | roll[deg] |
| Target | 1.1 | -0.9 | -19.4 | -0.0186 | -0.0040 | 0.0138 |

Positive $x$ is to the beam left from ideal beam; negative $y$ is the amount lower than beamline; negative $z$ is amount upstream from ideal target. Positive yaw is the counter clockwise rotation about the Y axis; negative pitch is the clockwise rotation about the X axis; positive roll is the clockwise rotation about the Z axis.

The ideal CEBAF coordinate for the target is shown below for reference.

| Component | Cebaf Ideal [meters] |  |  |
| :--- | :---: | :---: | :---: |
|  | $\mathbf{x [ m ]}$ | $\mathbf{y [ m ]}$ | $\mathbf{z [ m ]}$ |
| Target | -80.60000 | 103.35526 | -398.82153 |

The upstream beamline, IPM2H01 and IHA2H01 locations are shown below (z distance from 12G target in meters):

| Component | As-Found BFS |  |  | As-Found Angular [degrees] |  |  |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: |
|  | $\mathbf{x [ m m}]$ | $\mathbf{y}[\mathrm{mm}]$ | $\mathbf{z [ M ]}$ | yaw[deg] | pitch[deg] | roll[deg] |
| IPM2H01 | -0.02 | -0.20 | -9.249 | 0.01346 | 0.01518 | -0.04383 |
| IHA2H01 | -0.33 | -0.20 | -8.276 |  |  |  |
| beampipe | 0.85 | 0.63 | -11.271 |  |  |  |
| beampipe | 2.57 | 0.90 | -10.091 |  |  |  |
| beampipe | 0.02 | 0.26 | -9.477 |  |  |  |
|  | beampipe | -0.59 | 0.14 | -8.442 |  |  |


| Component | As-Found BFS |  |  |
| :--- | ---: | ---: | ---: |
|  | $\mathbf{x [ m m}]$ | $\mathbf{y [ m m}]$ | $\mathbf{z}[\mathbf{M}]$ |
| beampipe | 0.28 | -1.47 | -7.950 |
| beampipe | 1.20 | -0.59 | -7.403 |
| beampipe | -0.50 | 0.94 | -7.229 |
| beampipe | 0.28 | -1.47 | -7.950 |

