#  <br> ase <br> <br> Jefferson Lab Alignment Group <br> <br> Jefferson Lab Alignment Group <br> Data Transmittal 

TO: S. Wood, B. Sawatzky, D. Gaskell
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FROM: Kelly Tremblay
Checked: (jcd) $\quad$ \#: C1293

DETAILS:
Attached to this transmittal are the results from the June $16^{\text {th }}, 2010$ R3 wire chamber rotation repeatability survey. The goal of the survey was to check for movements directly at the detectors by measuring visible alignment targets at the production positions.

The data shows the center of the reference fiducial location which is different from the previous survey (memo C1286) where the data was transformed from observations on the end $Z$ plates. Additionally, these coordinates are given at the alignment target locations, not the hole centers which were calculated for memo C1286. Only detectors Leia and Hans were checked with the bulk of the information carried out on chamber Leia.

For the Leia data, the 5 production positions ( $0^{\circ}$ (home), $+45^{\circ},+90^{\circ},-45^{\circ},-90^{\circ}$ ) were measured once each to obtain the "standard" coordinates. After each move to $+/-45^{\circ}$ and $+/-90^{\circ}$, Leia was returned to the home position and measured there again. The detector would then return to the $+/-45^{\circ}$ or $+/-90^{\circ}$ position for a second set of measurements and then back to home.

Leia was also measured at the home position after the detector was slid along the arms then extended out again to measure the effect this would have on the reproducibility of the sliding motion.

Hans was measured at the $+/-90^{\circ}$ position with 1 repeated survey. Those results are compared.

The results show the coordinates at the production position for each wire chamber relative to the QTOR magnet center. The coordinates taken at the "standard" position are given, and the coordinate differences between these and the repeated position are shown as deltas.

The coordinates and differences are in millimeters with $X$ coordinate transverse to the beamline positive beam left, $Y$ in the vertical position, positive up and $Z$ along the beamline positive downstream,. The values for the deltas are repeated position minus the original.

| Leia Data |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Leia Home Original (0 degrees) |  |  |  |  |  |  |
| Target | $\mathrm{X}(\mathrm{mm})$ | Y (mm) | Z(mm) |  |  |  |
| A | -3097.8 | 1153.1 | 5133.5 |  |  |  |
| G | -2722.4 | -1145.5 | 4964.5 |  |  |  |
| H | -3098.5 | -1145.6 | 5133.5 |  |  |  |
| Repeat 1 on Home after -45 |  |  |  | Epoch - Home Orig |  |  |
| Target | X(mm) | $\mathrm{Y}(\mathrm{mm})$ | Z(mm) | X(mm) | $\mathrm{Y}(\mathrm{mm})$ | Z(mm) |
| A | -3098.0 | 1152.6 | 5133.5 | -0.2 | -0.5 | 0.0 |
| G | -2722.1 | -1145.9 | 4964.4 | 0.3 | -0.5 | -0.1 |
| H | -3098.2 | -1146.2 | 5133.4 | 0.2 | -0.6 | -0.1 |
|  |  |  |  |  |  |  |
| Repeat 2 on Home after -45 |  |  |  | Epoch - Home Orig |  |  |
| Target | X(mm) | $\mathrm{Y}(\mathrm{mm})$ | Z(mm) | $\mathrm{X}(\mathrm{mm})$ | $\mathrm{Y}(\mathrm{mm})$ | $\mathrm{Z}(\mathrm{mm})$ |
| A | -3098.1 | 1152.5 | 5133.4 | -0.2 | -0.6 | -0.1 |
| G | -2722.1 | -1146.1 | 4964.4 | 0.3 | -0.6 | -0.2 |
| H | -3098.2 | -1146.3 | 5133.3 | 0.3 | -0.7 | -0.2 |
|  |  |  |  |  |  |  |
| Repeat 1 on Home after -90 deg |  |  |  | Epoch - Home Orig |  |  |
| Target | X(mm) | $\mathrm{Y}(\mathrm{mm})$ | Z(mm) | $\mathrm{X}(\mathrm{mm})$ | $Y$ (mm) | Z(mm) |
| A | -3098.0 | 1152.6 | 5133.4 | -0.1 | -0.5 | -0.1 |
| G | -2722.1 | -1146.0 | 4964.4 | 0.3 | -0.5 | -0.1 |
| H | -3098.2 | -1146.2 | 5133.4 | 0.3 | -0.6 | -0.1 |
|  |  |  |  |  |  |  |
| Repeat 2 on Home after -90 deg |  |  |  | Epoch - Home Orig |  |  |
| Target | X(mm) | Y (mm) | Z(mm) | X(mm) | Y (mm) | $\mathrm{Z}(\mathrm{mm})$ |
| A | -3097.6 | 1153.6 | 5133.4 | 0.3 | 0.4 | -0.1 |
| G | -2722.3 | -1145.1 | 4964.4 | 0.1 | 0.3 | -0.1 |
| H | -3098.4 | -1145.2 | 5133.4 | 0.0 | 0.4 | -0.1 |
|  |  |  |  |  |  |  |
| Repeat 1 on Home after +45 |  |  |  | Epoch - Home Orig |  |  |
| Target | X(mm) | $\mathrm{Y}(\mathrm{mm})$ | Z(mm) | X(mm) | $\mathrm{Y}(\mathrm{mm})$ | Z(mm) |
| A | -3097.9 | 1153.2 | 5133.7 | -0.1 | 0.1 | 0.2 |
| G | -2722.5 | -1145.5 | 4964.7 | -0.1 | 0.0 | 0.2 |
| H | -3098.6 | -1145.6 | 5133.7 | -0.1 | 0.0 | 0.2 |
|  |  |  |  |  |  |  |
| Repeat 2 on Home after +45 |  |  |  | Epoch - Home Orig |  |  |
| Target | $\mathrm{X}(\mathrm{mm})$ | $\mathrm{Y}(\mathrm{mm})$ | Z(mm) | $\mathrm{X}(\mathrm{mm})$ | $Y(\mathrm{~mm})$ | Z(mm) |
| A | -3098.0 | 1153.2 | 5133.7 | -0.2 | 0.0 | 0.2 |
| G | -2722.5 | -1145.5 | 4964.7 | -0.1 | -0.1 | 0.2 |
| H | -3098.6 | -1145.7 | 5133.7 | -0.1 | -0.1 | 0.2 |


| Leia Data Continued |  |  |  | Epoch - Home Orig |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Repeat 1 on Home after +90 |  |  |  |  |  |  |
| Target | X(mm) | Y (mm) | Z(mm) | X(mm) | $\mathrm{Y}(\mathrm{mm})$ | Z(mm) |
| A | -3098.0 | 1153.1 | 5133.7 | -0.2 | -0.1 | 0.2 |
| G | -2722.5 | -1145.6 | 4964.8 | -0.1 | -0.1 | 0.2 |
| H | -3098.6 | -1145.8 | 5133.8 | -0.1 | -0.2 | 0.3 |
|  |  |  |  |  |  |  |
| Repeat 2 on Home after +90 |  |  |  | Epoch - Home Orig |  |  |
| Target | X(mm) | $\mathrm{Y}(\mathrm{mm})$ | Z(mm) | X(mm) | $\mathrm{Y}(\mathrm{mm})$ | Z(mm) |
| A | -3098.0 | 1153.1 | 5133.7 | -0.2 | -0.1 | 0.2 |
| G | -2722.5 | -1145.6 | 4964.7 | -0.1 | -0.2 | 0.2 |
| H | -3098.6 | -1145.8 | 5133.8 | -0.1 | -0.2 | 0.3 |


| Data at Standard Positions |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Leia at -45 degrees |  |  |  |  |  |  |
| Target | X(mm) | Y (mm) | Z(mm) |  |  |  |
| A | -1367.2 | 3007.1 | 5136.6 |  |  |  |
| B | -1102.3 | 2741.6 | 4965.4 |  |  |  |
| G | -2729.7 | 1117.9 | 4968.5 |  |  |  |
| H | -2995.3 | 1384.1 | 5137.8 |  |  |  |
|  |  |  |  |  |  |  |
| Leia at -45 degrees repeated |  |  |  | -45 repeat minus -45 original |  |  |
| Target | X(mm) | $\mathrm{Y}(\mathrm{mm})$ | Z(mm) | X(mm) | $\mathrm{Y}(\mathrm{mm})$ | $\mathrm{Z}(\mathrm{mm})$ |
| A | -1366.6 | 3007.3 | 5136.6 | 0.7 | 0.3 | 0.0 |
| B | -1101.7 | 2741.8 | 4965.4 | 0.6 | 0.2 | 0.0 |
| G | -2729.4 | 1118.5 | 4968.5 | 0.3 | 0.6 | 0.0 |
| H | -2994.9 | 1384.7 | 5137.7 | 0.3 | 0.6 | -0.1 |
|  |  |  |  |  |  |  |
| Leia at -90 degrees |  |  |  |  |  |  |
| Target | X(mm) | $Y$ (mm) | Z(mm) |  |  |  |
| A | 1160.5 | 3094.6 | 5135.1 |  |  |  |
| B | 1160.3 | 2719.6 | 4963.9 |  |  |  |
| G | -1138.4 | 2720.1 | 4968.9 |  |  |  |
| H | -1138.3 | 3096.2 | 5138.0 |  |  |  |
|  |  |  |  |  |  |  |
| Leia at -90 degrees repeated |  |  |  | -90 repeat minus -90 original |  |  |
| Target | X(mm) | Y (mm) | Z(mm) | $\mathrm{X}(\mathrm{mm})$ | $\mathrm{Y}(\mathrm{mm})$ | Z(mm) |
| A | 1160.8 | 3094.4 | 5134.9 | 0.3 | -0.1 | -0.3 |
| B | 1160.6 | 2719.4 | 4963.6 | 0.3 | -0.2 | -0.2 |
| G | -1138.3 | 2720.2 | 4968.8 | 0.2 | 0.1 | -0.1 |
| H | -1138.0 | 3096.3 | 5138.0 | 0.3 | 0.1 | 0.0 |



| Slide in and out at the home (0 degree) position |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Repeat 1 after sliding in and out |  |  |  | slide 1- original home |  |  |  |  |  |
| Target | X(mm) | $\mathrm{Y}(\mathrm{mm})$ | Z(mm) | X | Y | Z |  |  |  |
| A | -3090.7 | 1153.9 | 5133.7 | 7.1 | 0.7 | 0.2 |  |  |  |
| G | -2719.7 | -1145.5 | 4964.7 | 2.7 | 0.0 | 0.2 |  |  |  |
| H | -3095.8 | -1144.9 | 5133.8 | 2.6 | 0.7 | 0.3 |  |  |  |
|  |  |  |  |  |  |  |  |  |  |
| Repeat 2 after sliding in and out |  |  |  | slide 2 - original home |  |  | Slide 2 - Slide 1 values |  |  |
| Target | X(mm) | $\mathrm{Y}(\mathrm{mm})$ | Z(mm) | X | Y | Z | X | Y | Z |
| A | -3090.4 | 1153.9 | 5133.7 | 7.4 | 0.8 | 0.2 | 0.3 | 0.1 | 0.1 |
| G | -2719.6 | -1145.5 | 4964.7 | 2.8 | 0.0 | 0.2 | 0.2 | 0.0 | 0.1 |
| H | -3095.7 | -1144.9 | 5133.8 | 2.8 | 0.7 | 0.3 | 0.2 | 0.0 | 0.0 |
|  |  |  |  |  |  |  |  |  |  |
| Repeat 3 after sliding in and out |  |  |  | slide 3-original home |  |  | Slide 3-Slide 1 values |  |  |
| Target | $\mathrm{X}(\mathrm{mm})$ | $\mathrm{Y}(\mathrm{mm})$ | Z(mm) | X | Y | Z | X | Y | Z |
| A | -3090.2 | 1154.0 | 5133.7 | 7.6 | 0.8 | 0.2 | 0.5 | 0.1 | 0.1 |
| G | -2719.5 | -1145.4 | 4964.7 | 2.9 | 0.0 | 0.2 | 0.2 | 0.0 | 0.1 |
| H | -3095.6 | -1144.8 | 5133.8 | 2.9 | 0.8 | 0.3 | 0.3 | 0.1 | 0.0 |



