

## Jefferson Lab Alignment Group

## **Data Transmittal**

TO: H. Egiyen, T. Whitlatch DATE: 12 Jul 2017

FROM: Jacob Walker Checked: #: D1802

DATA: Inspection\HallD\Tagger Goniometer\170629A

## **DETAILS:**

Below are the results of the recent goniometer stage alignment carried out in the survey lab. A rotation only coordinate system was established on the goniometer using the following; rX.pitch axis of rotation defines yaw and roll. rY.roll axis of rotation defines pitch. **Note:** rX pitch, rY roll, and rZ yaw axis of rotations listed below are as labeled on the drive motors. A negative pitch angle is clockwise looking from the left. A negative yaw angle is clockwise looking from above. A positive roll angle is clockwise looking from upstream. New home values are listed under the corresponding motor.

XY Stage Plane:

Pitch =  $-0.004^{\circ}$ , Yaw =  $0.021^{\circ}$ 

rX.pitch:

 $Yaw = 0.000^{\circ}$ ,  $Roll = 0.000^{\circ}$ 

Home =  $0.48^{\circ}$ 

rZ.yaw:

Pitch =  $0.006^{\circ}$ , Roll =  $0.108^{\circ}$ 

Home =  $-0.06^{\circ}$ 

rY.roll:

Pitch =  $0.000^{\circ}$ , Yaw =  $0.029^{\circ}$