

New approaches to global PDF analysis

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Outline

- Motivation — why the need for a new paradigm?
- Bayesian approach to fitting
 - single-fit (Hessian) vs. Monte Carlo approaches
 - shortcomings of Hessian (Gaussian) approach
- Incompatible data sets
 - “tolerance” factors
(uncertainties should not depend on # of parameters!)
- Monte Carlo methods
 - iterative MC, nested sampling, ...
- Generalization to non-Gaussian likelihoods
 - disjoint probabilities, empirical Bayes, ...
- Outlook

Motivation

- With limited number of observables and *finite statistics*, need a robust analysis framework to extract meaningful parton information from experiment
- Over the first ~ 2 – 3 decades of global PDF analysis efforts, χ^2 minimization (single-fit) analysis (with Hessian error propagation) has generally been sufficient to map out global characteristics of partonic structure
→ *e.g.* shapes of quark PDFs from DIS, where data are plentiful
- A major challenge has been to characterize PDF uncertainties — in a statistically meaningful way — in the presence of *tensions* among data sets

Motivation

- Previous attempts sought to address tensions in data sets by introducing
 - “tolerance” factors (artificially inflating PDF errors)
 - “neural net” parametrization (instead of polynomial parametrization), together with MC techniques
- However, to address the problem in a more statistically rigorous way, one requires going *beyond* the standard χ^2 minimization paradigm
 - utilize modern techniques based on Bayesian statistics!

Motivation

- In the near future, standard χ^2 minimization techniques will be unsuitable — even in the absence of tensions — *e.g.* for

- simultaneous analysis of collinear distributions
(unpolarized & polarized PDFs, fragmentation functions)

→ “JAM17”: *Jake Ethier (Tuesday)*

- new types of observables — TMDs or GPDs —
that will involve $> \mathcal{O}(10^5)$ data points, with $\mathcal{O}(10^3)$
parameters

Motivation

- Typically PDF parametrizations are nonlinear functions of the PDF parameters, *e.g.*

$$xf(x, \mu) = Nx^\alpha(1-x)^\beta P(x)$$

where P is a polynomial *e.g.* $P(x) = 1 + \epsilon\sqrt{x} + \eta x$,
or Chebyshev, neural net, ...

→ have multiple local minima present in the χ^2 function

- Robust parameter estimation that thoroughly scans over a realistic parameter space, including multiple local minima, is only possible using MC methods!
- Need more reliable algorithms — “PDFs beyond the LHC”!

Bayesian approach to fitting

Bayesian approach to fitting

- Analysis of data requires estimating expectation values E and variances V of “observables” \mathcal{O} (= PDFs, FFs) which are functions of parameters \vec{a}

$$E[\mathcal{O}] = \int d^n a \mathcal{P}(\vec{a}|\text{data}) \mathcal{O}(\vec{a})$$
$$V[\mathcal{O}] = \int d^n a \mathcal{P}(\vec{a}|\text{data}) [\mathcal{O}(\vec{a}) - E[\mathcal{O}]]^2$$

“Bayesian master formulas”

- Using Bayes’ theorem, probability distribution \mathcal{P} given by

$$\mathcal{P}(\vec{a}|\text{data}) = \frac{1}{Z} \mathcal{L}(\text{data}|\vec{a}) \pi(\vec{a})$$

in terms of the likelihood function \mathcal{L}

Bayesian approach to fitting

■ Likelihood function

$$\mathcal{L}(\text{data}|\vec{a}) = \exp\left(-\frac{1}{2}\chi^2(\vec{a})\right)$$

is a Gaussian form in the data, with χ^2 function

$$\chi^2(\vec{a}) = \sum_i \left(\frac{\text{data}_i - \text{theory}_i(\vec{a})}{\delta(\text{data})} \right)^2$$

with priors $\pi(\vec{a})$ and “evidence” Z

$$Z = \int d^n a \mathcal{L}(\text{data}|\vec{a}) \pi(\vec{a})$$

→ Z tests if *e.g.* an n -parameter fit is statistically different from $(n+1)$ -parameter fit

Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:

Maximum Likelihood

(χ^2 minimization)

Monte Carlo

Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:

Maximum Likelihood

(χ^2 minimization)

→ maximize probability distribution \mathcal{P} by minimizing χ^2
for a set of best-fit parameters \vec{a}_0

$$E [\vec{a}] = \vec{a}_0$$

Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:

Maximum Likelihood

(χ^2 minimization)

- maximize probability distribution \mathcal{P} by minimizing χ^2 for a set of best-fit parameters \vec{a}_0

$$E [\vec{a}] = \vec{a}_0$$

- if \mathcal{O} is \approx linear in the parameters, and if probability is symmetric in all parameters

$$E [\mathcal{O}(\vec{a})] \approx \mathcal{O}(\vec{a}_0)$$

Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:

Maximum Likelihood

(χ^2 minimization)

→ variance computed by expanding $\mathcal{O}(\vec{a})$ about \vec{a}_0
e.g. in 1 dimension have “master formula”

$$V[\mathcal{O}] \approx \frac{1}{4} \left[\mathcal{O}(a + \delta a) - \mathcal{O}(a - \delta a) \right]^2$$

where

$$\delta a^2 = V[a]$$

Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:

Maximum Likelihood

(χ^2 minimization)

→ generalization to multiple dimensions via Hessian approach:

find set of (orthogonal) contours in parameter space around \vec{a}_0 such that \mathcal{L} along each contour is parametrized by statistically independent parameters — directions of contours given by eigenvectors \hat{e}_k of Hessian matrix H , with elements

$$H_{ij} = \frac{1}{2} \left. \frac{\partial^2 \chi^2(\vec{a})}{\partial a_i \partial a_j} \right|_{\vec{a}=\vec{a}_0}$$

and contours parametrized as $\Delta a^{(k)} = a^{(k)} - a_0 = t_k \frac{\hat{e}_k}{\sqrt{v_k}}$,
with v_k eigenvalues of H

Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:

Maximum Likelihood

(χ^2 minimization)

→ basic assumption: \mathcal{P} factorizes along each eigendirection

$$\mathcal{P}(\Delta a) \approx \prod_k \mathcal{P}_k(t_k)$$

where

$$\mathcal{P}_k(t_k) = \mathcal{N}_k \exp \left[-\frac{1}{2} \chi^2 \left(a_0 + t_k \frac{\hat{e}_k}{\sqrt{v_k}} \right) \right]$$

note: in quadratic approximation for χ^2 , this becomes a normal distribution

Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:

Maximum Likelihood

(χ^2 minimization)

→ uncertainties on \mathcal{O} along each eigendirection
(assuming linear approximation)

$$(\Delta \mathcal{O}_k)^2 \approx \frac{1}{4} \left[\mathcal{O} \left(a_0 + T_k \frac{\hat{e}_k}{\sqrt{v_k}} \right) - \mathcal{O} \left(a_0 - T_k \frac{\hat{e}_k}{\sqrt{v_k}} \right) \right]^2$$

where T_k is finite step size in t_k , with total variance

$$V[\mathcal{O}] = \sum_k (\Delta \mathcal{O}_k)^2$$

Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:

Monte Carlo

- in practice, generally one has $E[\mathcal{O}(\vec{a})] \neq \mathcal{O}(E[\vec{a}])$
so the maximal likelihood method will sometimes fail
- Monte Carlo approach samples parameter space and assigns weights w_k to each set of parameters a_k
- expectation value and variance are then weighted averages

$$E[\mathcal{O}(\vec{a})] = \sum_k w_k \mathcal{O}(\vec{a}_k), \quad V[\mathcal{O}(\vec{a})] = \sum_k w_k (\mathcal{O}(\vec{a}_k) - E[\mathcal{O}])^2$$

Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:

Maximum Likelihood

(χ^2 minimization)

- fast
- assumes Gaussianity
- no guarantee that global minimum has been found
- errors only characterize local geometry of χ^2 function

Monte Carlo

- slow
- does not rely on Gaussian assumptions
- includes all possible solutions
- accurate

Incompatible data sets

Incompatible data sets

- Incompatible data sets can arise because of errors in determining central values, or underestimation of systematic experimental uncertainties
→ requires some sort of modification to standard statistics
- Often one modifies the master formula by introducing a “tolerance” factor T

$$V[\mathcal{O}] \rightarrow T^2 V[\mathcal{O}]$$

e.g. for one dimension

$$V[\mathcal{O}] = \frac{T^2}{4} \left[\mathcal{O}(a + \delta a) - \mathcal{O}(a - \delta a) \right]^2$$

→ effectively modifies the likelihood function

Incompatible data sets

- Simple example: consider observable m , and two measurements

$$(m_1, \delta m_1), \quad (m_2, \delta m_2)$$

→ compute exactly the χ^2 function

$$\chi^2 = \left(\frac{m - m_1}{\delta m_1} \right)^2 + \left(\frac{m - m_2}{\delta m_2} \right)^2$$

and, from Bayesian master formula, the mean value

$$E[m] = \frac{m_1 \delta m_2^2 + m_2 \delta m_1^2}{\delta m_1^2 + \delta m_2^2}$$

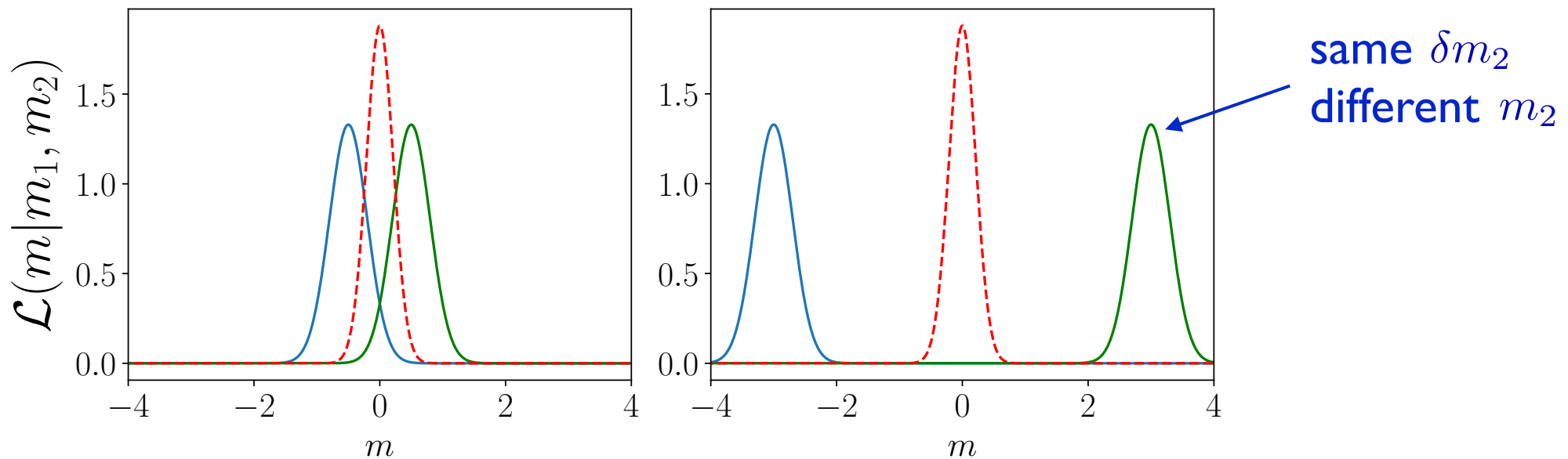
and variance

$$V[m] = H^{-1} = \frac{\delta m_1^2 \delta m_2^2}{\delta m_1^2 + \delta m_2^2}$$

does not
depend on
 $m_1 - m_2$!

Incompatible data sets

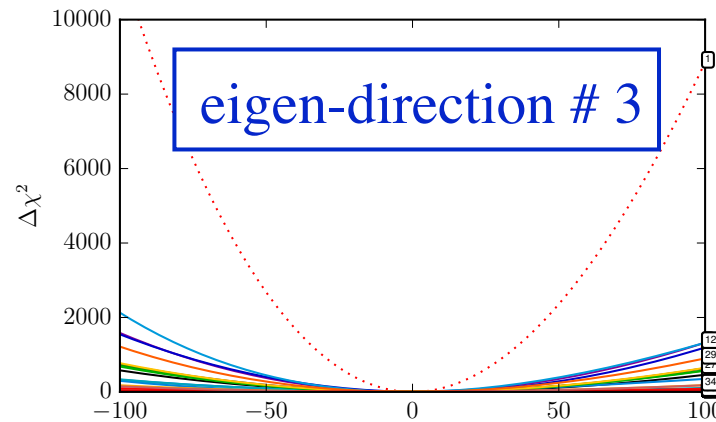
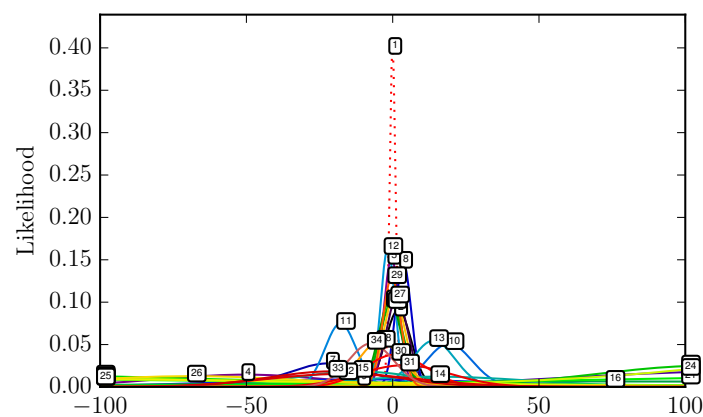
- Simple example: consider observable m , and two measurements $(m_1, \delta m_1)$, $(m_2, \delta m_2)$



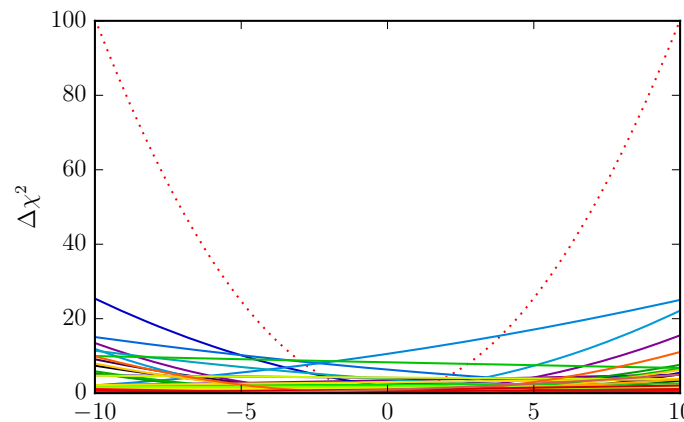
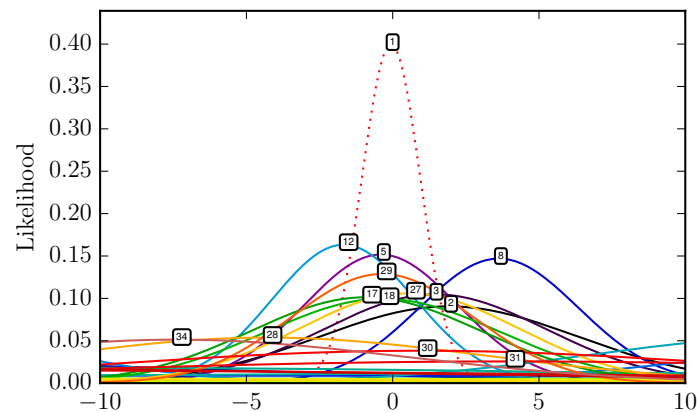
- total uncertainty remains independent of degree of (in)compatibility of data
- Gaussian likelihood gives unrealistic representation of true uncertainty

Incompatible data sets

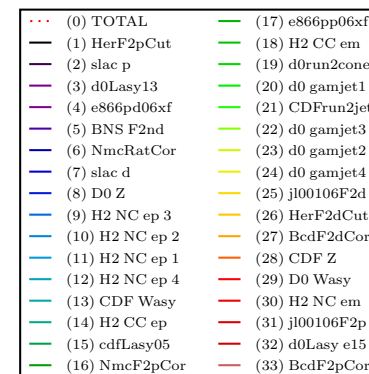
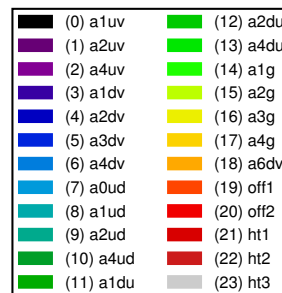
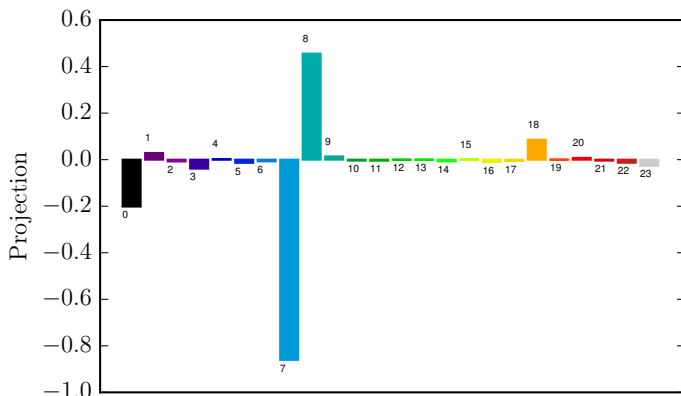
Realistic example: recent CJ (CTEQ-JLab) global PDF analysis



→ 24 parameters,
33 data sets

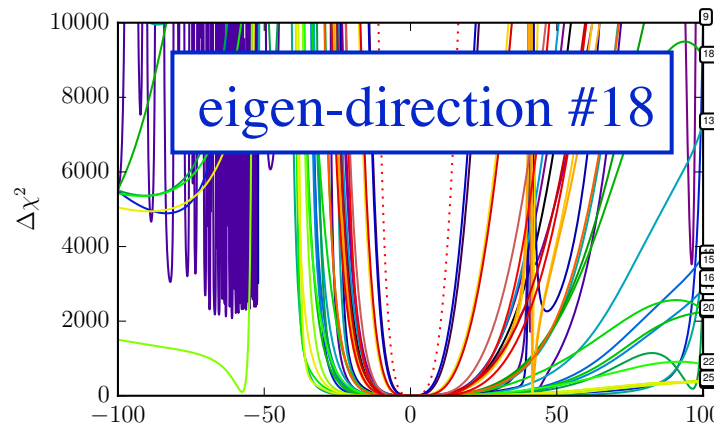
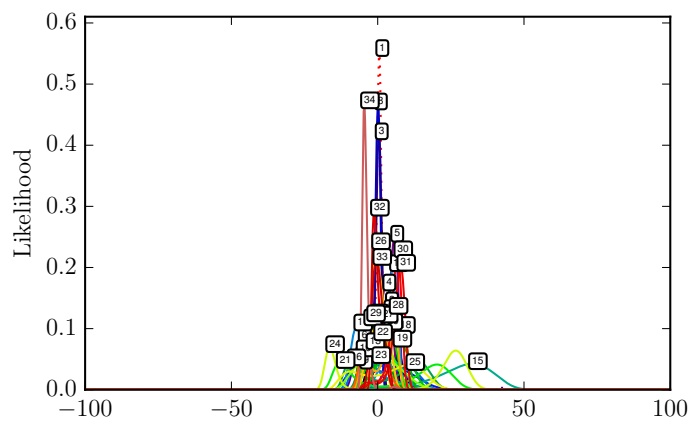


→ data sets
compatible
along this
e-direction

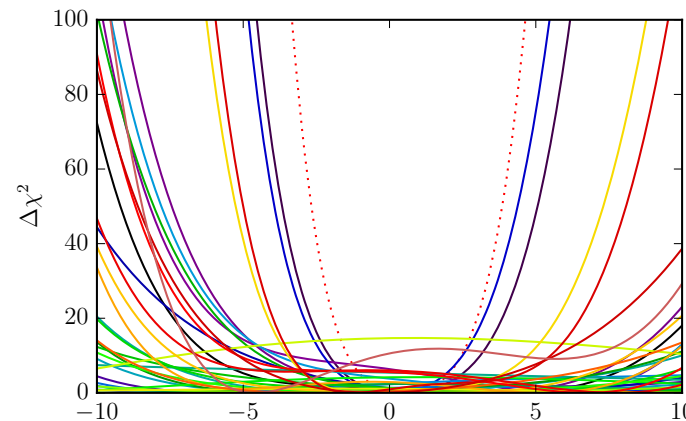
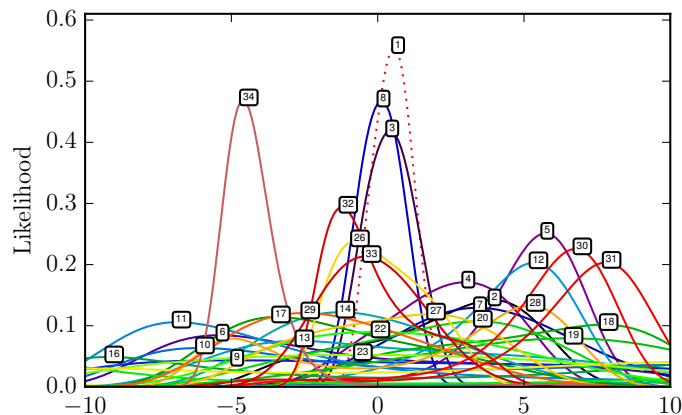


Incompatible data sets

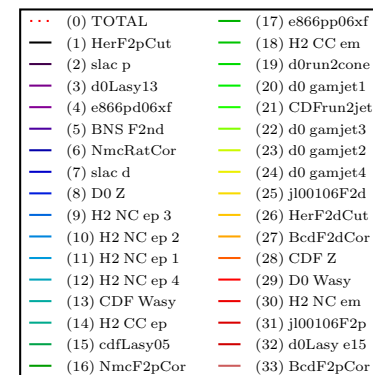
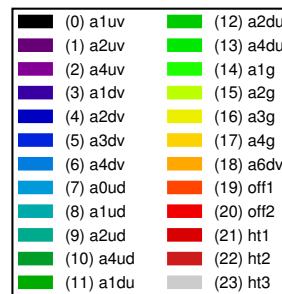
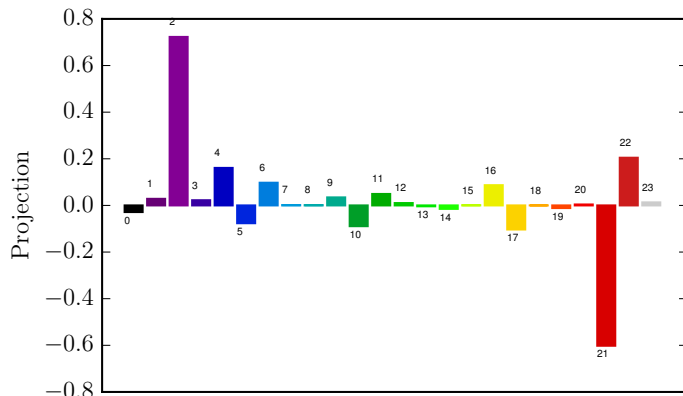
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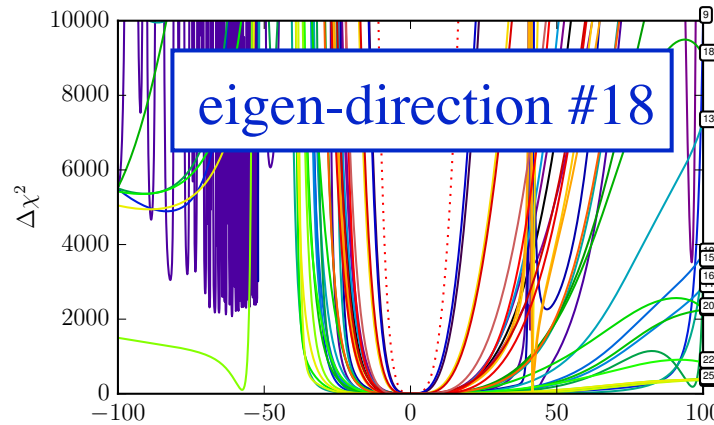
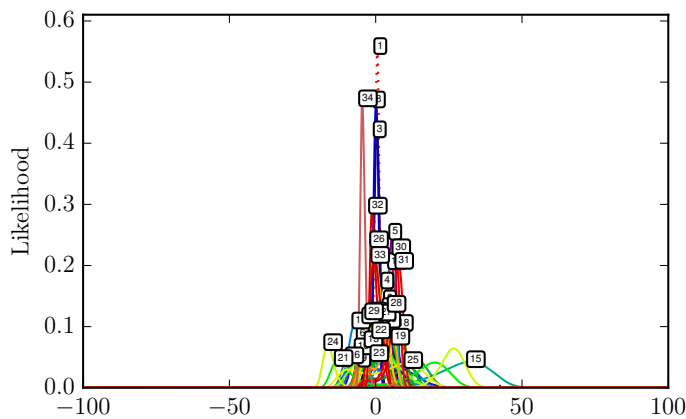


→ data sets not
compatible
along this
e-direction

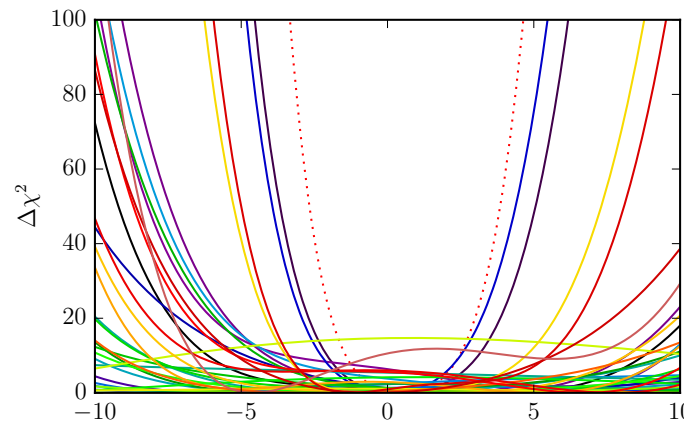
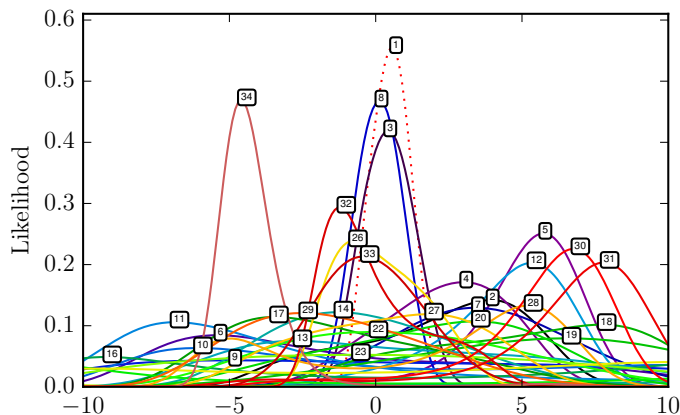


Incompatible data sets

■ Realistic example: recent CJ (CTEQ-JLab) global PDF analysis



→ 24 parameters,
33 data sets



→ data sets not
compatible
along this
e-direction

→ standard Gaussian likelihood incapable of accounting for underestimated individual errors (leading to incompatible data sets)
— not designed for such scenarios!

Incompatible data sets

■ Two ways in which tolerance factors usually implemented

- CTEQ “tolerance criteria”
(variations adopted by other groups, *e.g.*, MMHT, CJ)

Pumplin, Stump, Huston, Lai, Nadolsky, Tung
JHEP 07 (2002) 012

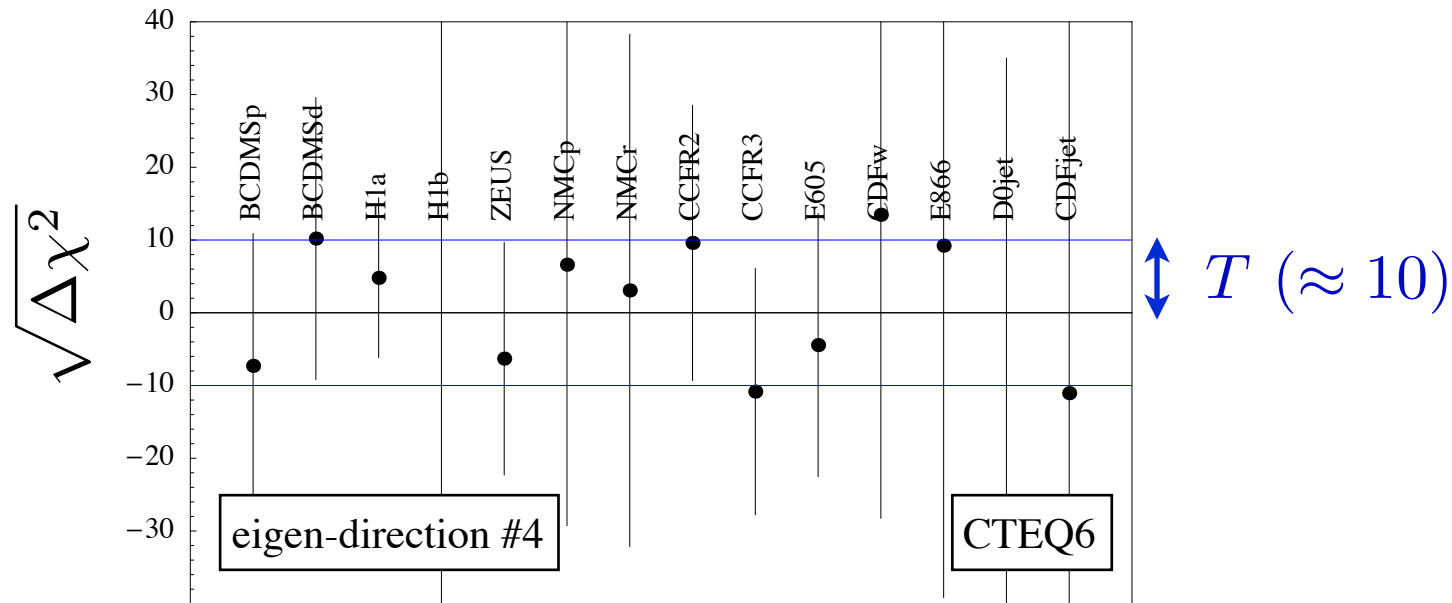
- scaling of $\Delta\chi^2$ with number of parameters
(or number of degrees of freedom)

e.g. Brodsky, Gardner
PRL (Comment) 116, 019101 (2016)

JDHLM assess their PDF errors using a tolerance criteria of $\Delta\chi^2 = 1$ at 1σ ; however, the actual value of $\Delta\chi^2$ to be employed depends on the number of parameters to be simultaneously determined in the fit. This is illustrated in Table 38.2 of Ref. [15] and is used broadly, noting, *e.g.*, Refs. [16–19]. Ref. [7] employs the CT10 PDF analysis [20], so that it contains 25 parameters, plus one for intrinsic charm. Figure 38.2 of Ref. [15] then shows that $\Delta\chi^2 \approx 29$ at 1σ (68% CL), whereas $\Delta\chi^2 \approx 36$ at 90% CL. Ref. [7] uses the criterion $\Delta\chi^2 > 100$, determined on empirical grounds, to indicate a poor fit. JDHLM employs the framework of Ref. [21] which contains 25 parameters for the PDFs and 12 for the higher-twist contributions, so that a much larger tolerance than $\Delta\chi^2 = 1$ is warranted.

Incompatible data sets

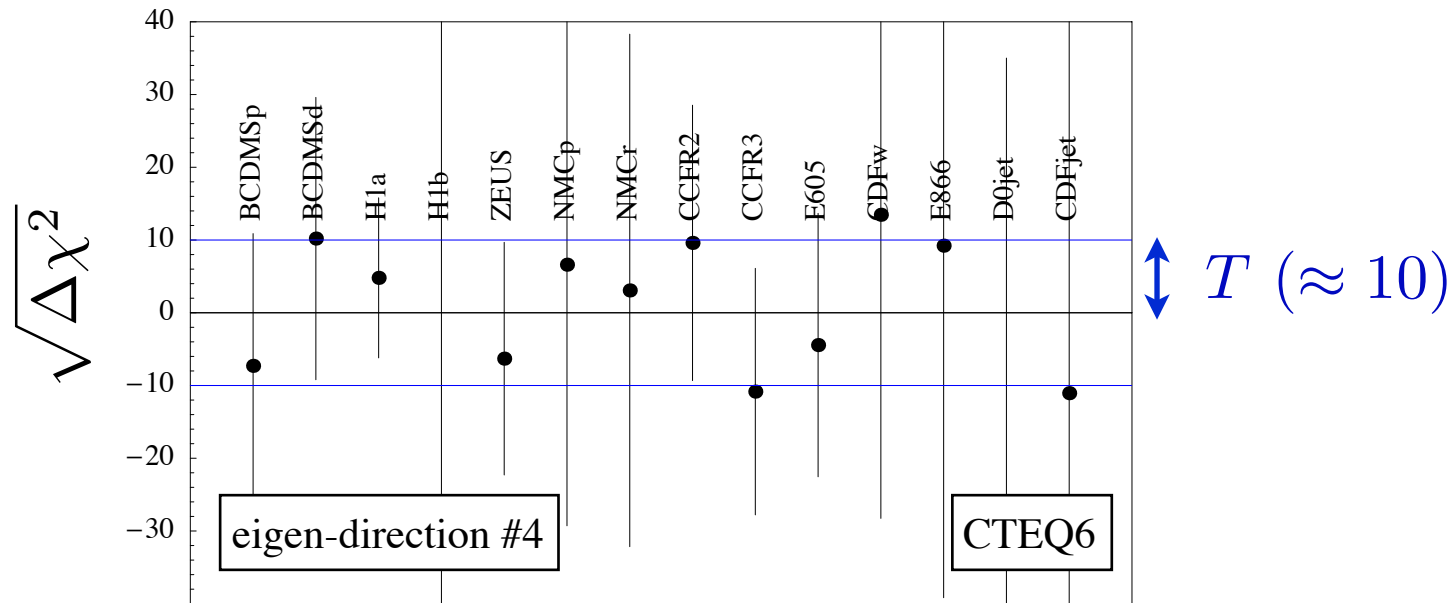
■ CTEQ tolerance criteria



- for each experiment, find minimum χ^2 along given e-direction
- from χ^2 distribution determine 90% CL for each experiment
- along each side of e-direction, determine maximum range d_k^\pm allowed by the most constraining experiment
- T computed by averaging over all d_k^\pm (typically $T \sim 5 - 10$)

Incompatible data sets

■ CTEQ tolerance criteria



■ This approach is *not consistent* with Gaussian likelihood

→ no clear Bayesian interpretation of uncertainties
(ultimately, a prescription...)

Incompatible data sets

- Scaling of $\Delta\chi^2$ with # of parameters: “ $\Delta\chi^2$ paradox”

- Simple example: two parameters θ_i ($i = 1, 2$)
with mean values μ_i and standard deviation σ_i

→ joint probability distribution

$$\mathcal{P}(\theta_1, \theta_2) = \prod_{i=1,2} \frac{1}{\sqrt{2\pi\sigma_i^2}} \exp \left[-\frac{1}{2} \left(\frac{\theta_i - \mu_i}{\sigma_i} \right)^2 \right]$$

→ change variables $\theta_i \rightarrow t_i = (\theta_i - \mu_i)/\sigma_i$ and use
polar coordinates $r^2 = t_1^2 + t_2^2$, $\phi = \tan^{-1}(t_2/t_1)$

$$d\theta_1 d\theta_2 \mathcal{P}(\theta_1, \theta_2) = \frac{d\phi}{2\pi} r dr \exp \left[-\frac{1}{2} r^2 \right]$$

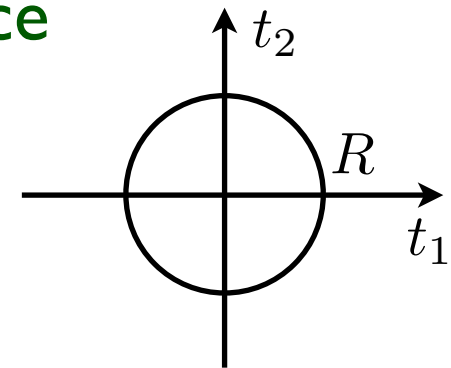
Incompatible data sets

■ Scaling of $\Delta\chi^2$ with # of parameters: “ $\Delta\chi^2$ paradox”

→ confidence volume

$$\begin{aligned} \text{CV} &\equiv \int d\theta_1 d\theta_2 \mathcal{P}(\theta_1, \theta_2) = \int_0^R dr r \exp\left[-\frac{1}{2}r^2\right] \\ &= 68\% \text{ for } R = 2.279 \end{aligned}$$

→ note that $R^2 = t_1^2 + t_2^2 \equiv \chi^2$, so that confidence region for parameters $\max[t_i] = R$



→ implies that $\theta_i = \mu_i \pm \sigma_i R$, which contradicts original premise that $\theta_i = \mu_i \pm \sigma_i$!

Incompatible data sets

- Scaling of $\Delta\chi^2$ with # of parameters: “ $\Delta\chi^2$ paradox”

→ to resolve paradox, use Bayesian master formulas

$$\begin{aligned} E[\theta_i] &= \int_0^{2\pi} \frac{d\phi}{2\pi} \int_0^\infty dr \mathcal{P}(r, \phi) \theta_i \\ &= \int_0^{2\pi} \frac{d\phi}{2\pi} \int_0^\infty dr r e^{-r^2/2} (\mu_i + t_i \sigma_i) = \mu_i \quad \checkmark \end{aligned}$$

Incompatible data sets

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$$\begin{aligned} E[\theta_i] &= \int_0^{2\pi} \frac{d\phi}{2\pi} \int_0^\infty dr \mathcal{P}(r, \phi) \theta_i \\ &= \int_0^{2\pi} \frac{d\phi}{2\pi} \int_0^\infty dr r e^{-r^2/2} (\mu_i + t_i \sigma_i) = \mu_i \quad \checkmark \end{aligned}$$

$$\begin{aligned} V[\theta_i] &= \int_0^{2\pi} \frac{d\phi}{2\pi} \int_0^\infty dr \mathcal{P}(r, \phi) (\theta_i - \mu_i)^2 \\ &= \int_0^{2\pi} \frac{d\phi}{2\pi} \int_0^\infty dr r e^{-r^2/2} (t_i \sigma_i)^2 = \sigma_i^2 \quad \checkmark \end{aligned}$$

Incompatible data sets

- Scaling of $\Delta\chi^2$ with # of parameters: “ $\Delta\chi^2$ paradox”
 - no paradox if use $\Delta\chi^2 = 1$ for any number of parameters to characterize the 1σ CL
 - only consistent tolerance for Gaussian likelihood is $T = 1$

To summarize standard maximum likelihood method...

- Gradient search (in parameter space) depends how “good” the starting point is
 - for ~ 30 parameters trying different starting points is impractical, if do not have some information about shape
- Common to free parameters initially, then freeze those not sensitive to data (χ^2 flat locally)
 - introduces bias, does not guarantee that flat χ^2 globally
- Cannot guarantee solution is unique
- Error propagation characterized by quadratic χ^2 near minimum
 - no guarantee this is quadratic globally (*e.g.* Student t -distribution?)
- Introduction of tolerance modifies Gaussian statistics

Monte Carlo methods

Monte Carlo

- Designed to faithfully compute Bayesian master formulas
- Do not assume a single minimum, include all possible solutions (with appropriate weightings)
- Do not assume likelihood is Gaussian in parameters
- Allows likelihood analysis to be extended to address tensions among data sets via Bayesian inference
- More computationally demanding compared with Hessian method

Monte Carlo

- First group to use MC for global PDF analysis was NNPDF, using neural network to parametrize $P(x)$ in

$$f(x) = N x^\alpha (1 - x)^\beta P(x)$$

— α, β are fitted “preprocessing coefficients”

- Iterative Monte Carlo (IMC), developed by JAM Collaboration, variant of NNPDF, tailored to non-neutral net parametrizations

→ *J. Ethier*

- Markov Chain MC (MCMC) / Hybrid MC (HMC)
— recent “proof of principle” analysis, ideas from lattice QCD

*Gbedo, Mangin-Brinet,
PRD 96, 014015 (2017)*

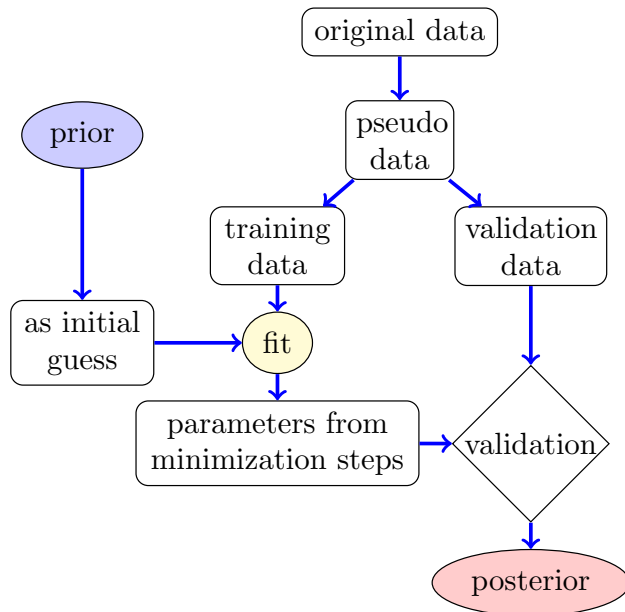
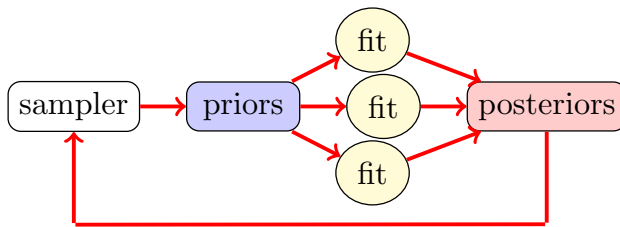
- Nested sampling (NS) — computes integrals in Bayesian master formulas (for E , V , Z) explicitly

Skilling (2004)

Iterative Monte Carlo (IMC)

- Use traditional functional form for input distribution shape, but sample significantly larger parameter space than possible in single-fit analyses

Iterative Monte Carlo (IMC)



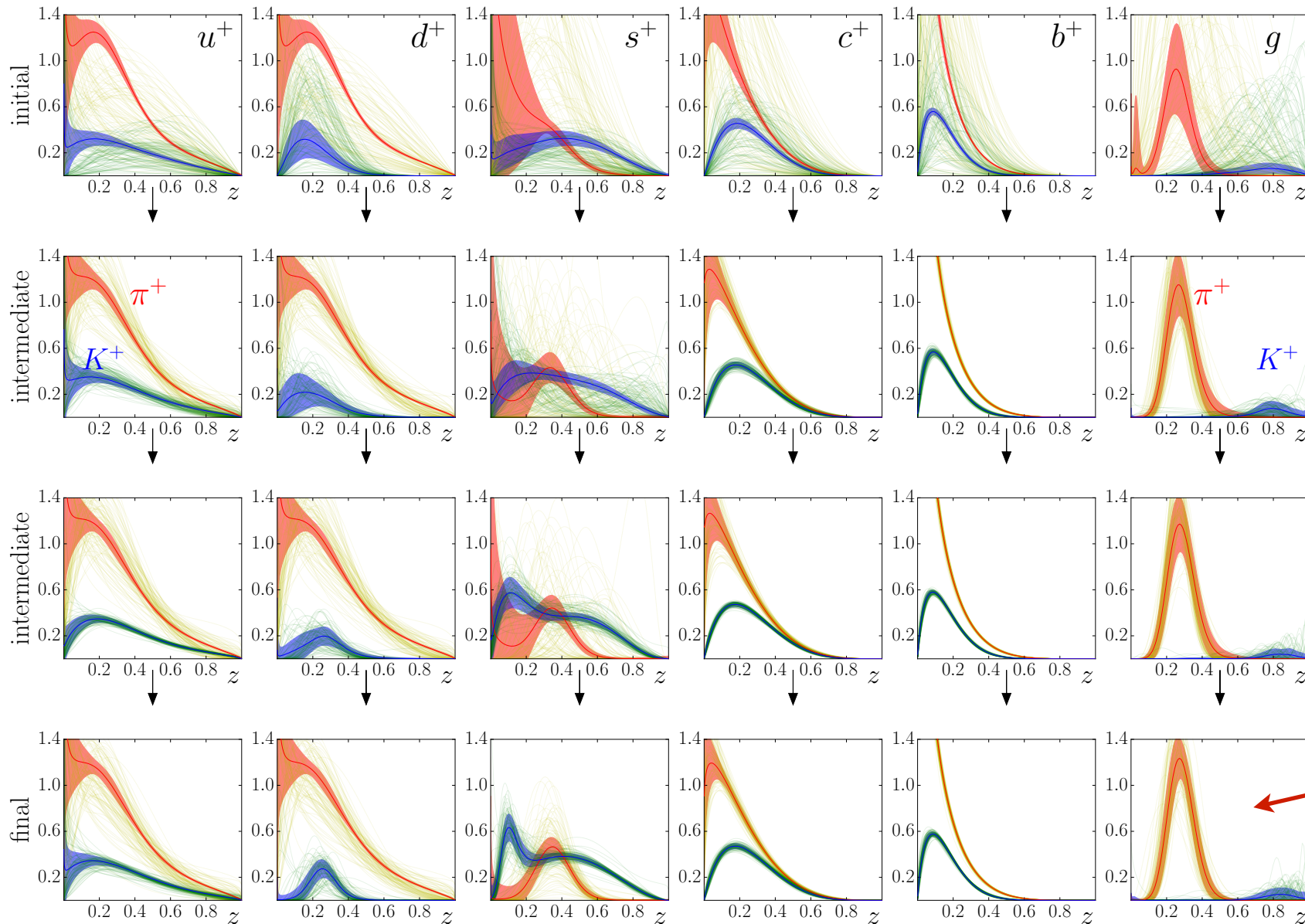
→ no assumptions for exponents

→ cross-validation to avoid overfitting

→ iterate until convergence criteria satisfied

Iterative Monte Carlo (IMC)

■ *e.g.* of convergence (for fragmentation functions) in IMC



Sato et al.
PRD 94, 114004
(2016)

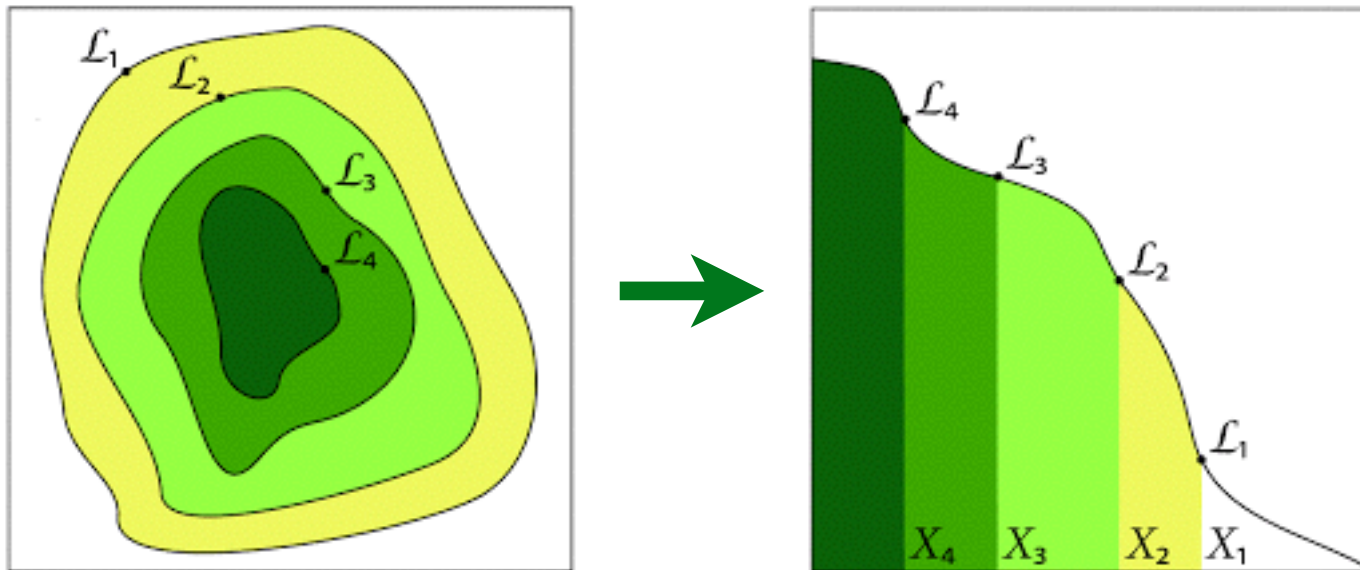
~ 20
iterations

Nested Sampling

- Basic idea: transform n -dimensional integral to 1-D integral

$$Z = \int d^n a \mathcal{L}(\text{data}|\vec{a}) \pi(\vec{a}) = \int_0^1 dX \mathcal{L}(X)$$

where *prior volume* $dX = \pi(\vec{a}) d^n a$



such that $0 < \dots < X_2 < X_1 < X_0 = 1$

Feroz et al.
arXiv:1306.2144 [astro-ph]

Nested Sampling

- Approximate evidence by a weighted sum

$$Z \approx \sum_i \mathcal{L}_i w_i \quad \text{with weights} \quad w_i = \frac{1}{2}(X_{i-1} - X_{i+1})$$

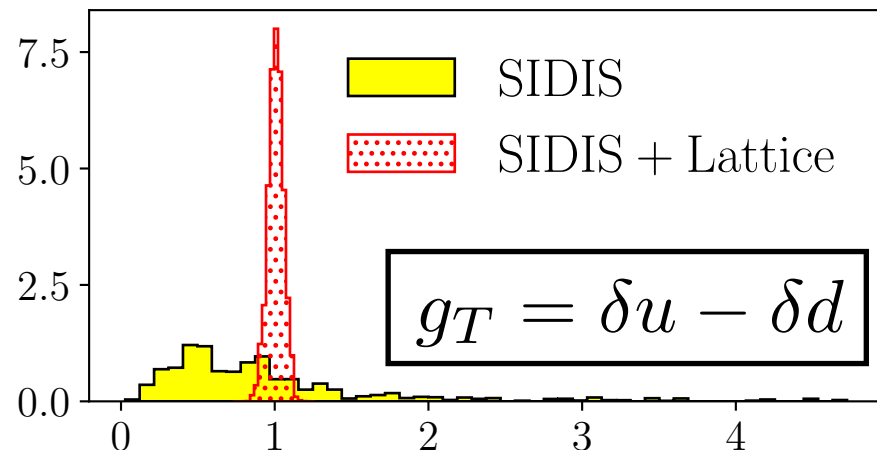
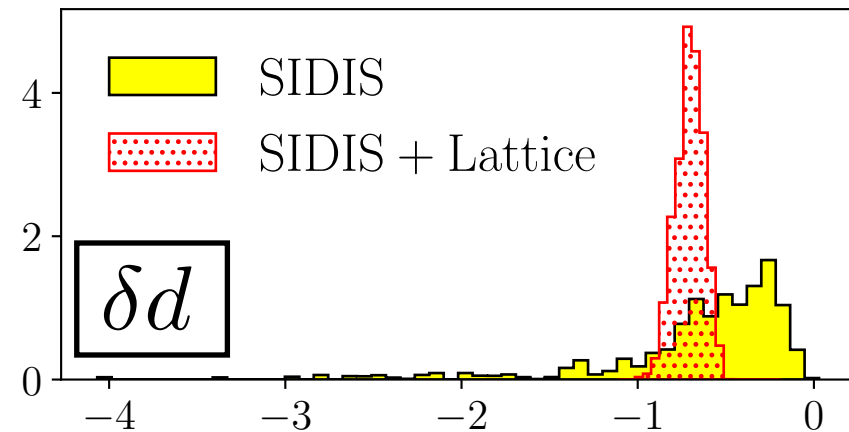
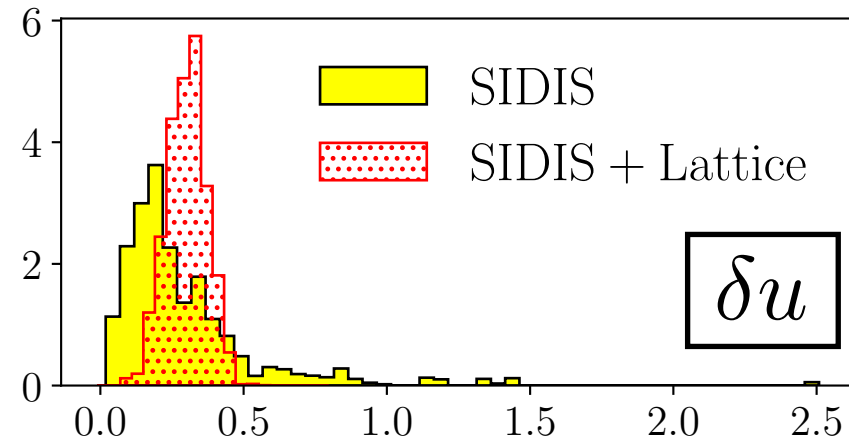
- Algorithm:

- randomly select samples from full prior s.t. initial volume $X_0 = 1$
- for each iteration, remove point with lowest \mathcal{L}_i , replacing it with point from prior with constraint that its $\mathcal{L} > \mathcal{L}_i$
- repeat until entire prior volume has been traversed
- can be parallelized
- performs better than VEGAS for large dimensions
- increasingly used in fields outside of (nuclear) analysis

Nested Sampling

- Recent application in global analysis of transversity TMD PDF

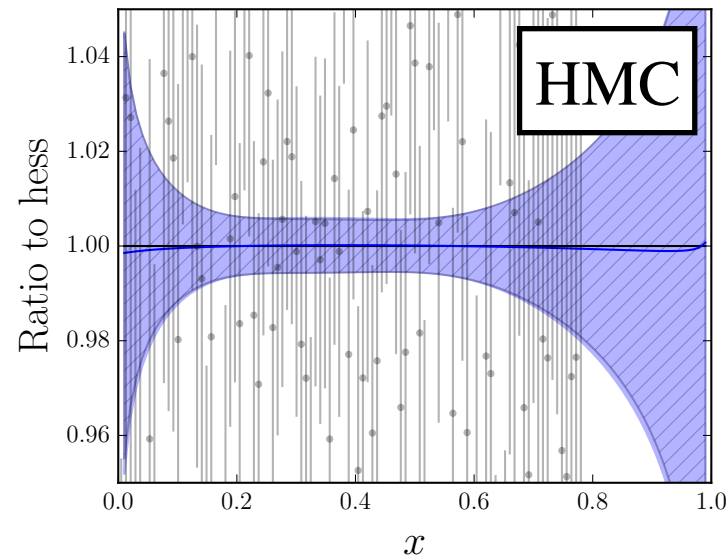
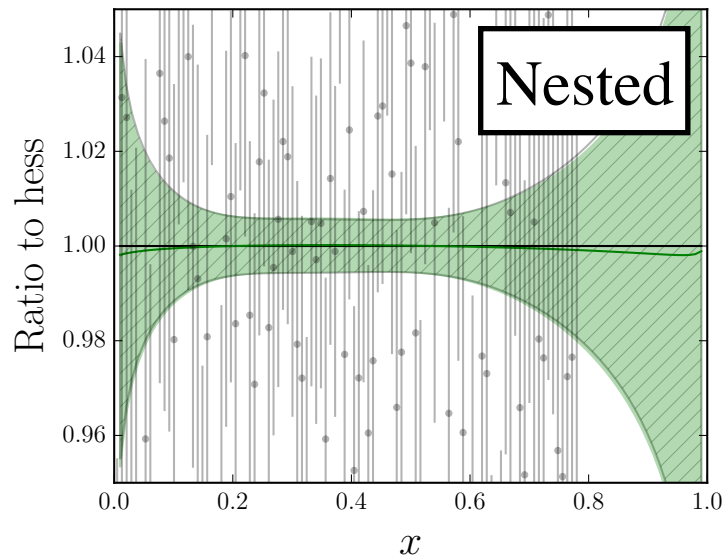
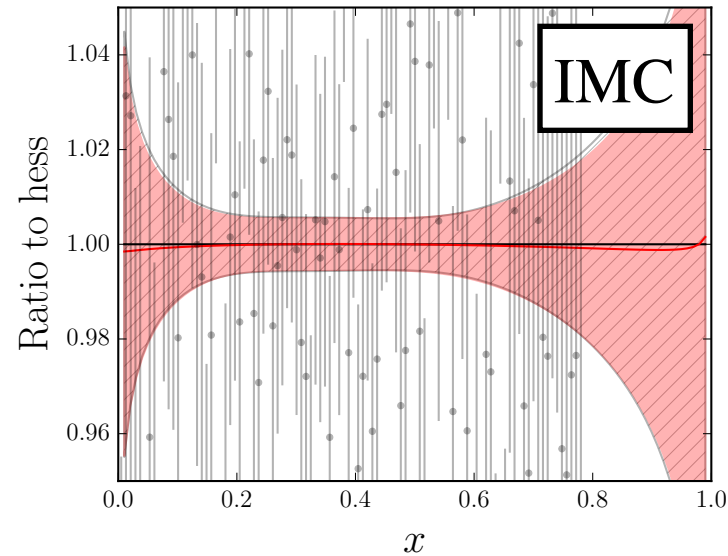
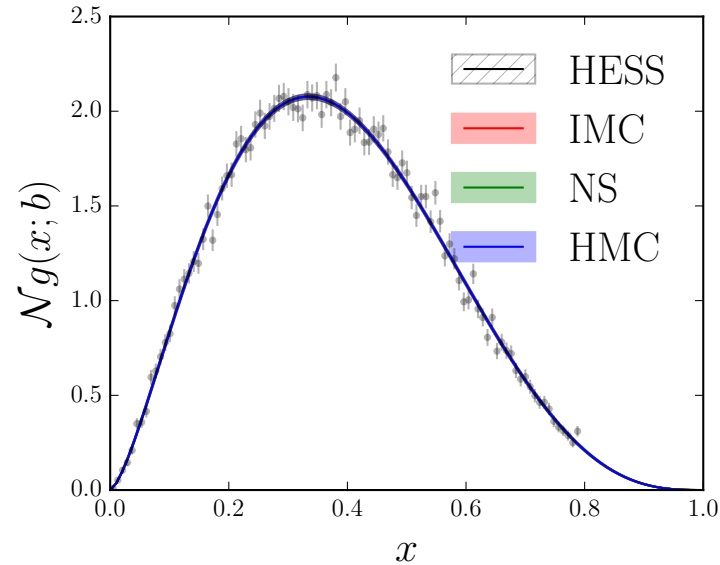
→ *H.-W. Lin*



*Lin, WM, Prokudin,
Sato, Shows (2017)*

MC Error Analysis

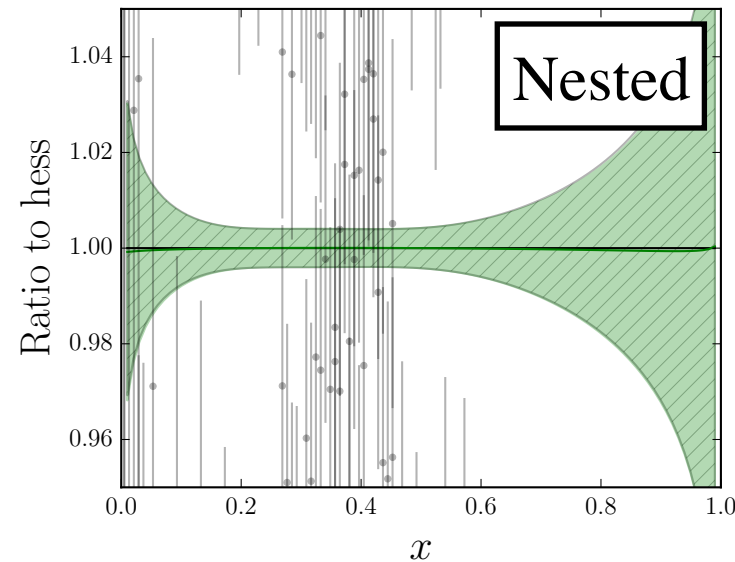
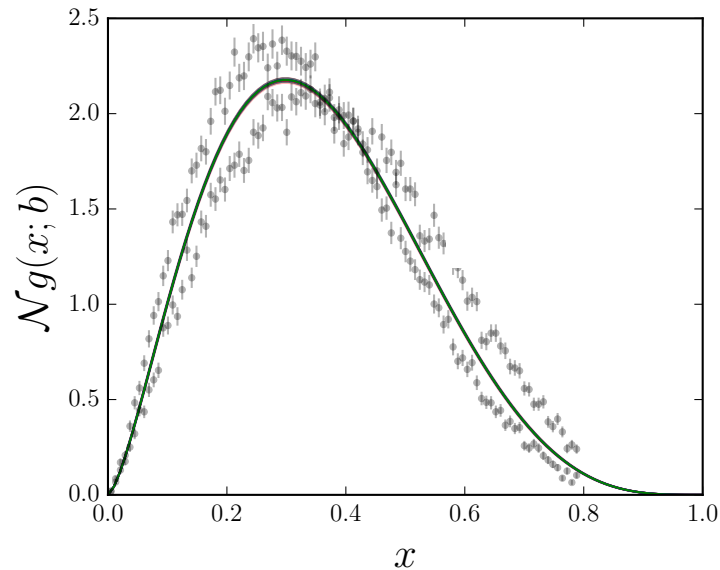
- Assuming a single minimum, a Hessian or MC analysis *must* give same results, if using same likelihood function
 - analysis of pseudodata, generated using Gaussian distribution



MC Error Analysis

- Assuming a single minimum, a Hessian or MC analysis *must* give same results, if using same likelihood function

→ also for discrepant data



→ almost identical uncertainty bands for Hessian and for MC!

MC Error Analysis

- Assuming a single minimum, a Hessian or MC analysis *must* give same results, if using same likelihood function
- Approaches that use Hessian + tolerance factor not consistent with Gaussian likelihood function
- NNPDF group claim that within their neural net MC methodology, no need for a tolerance factor, since uncertainties similar to other groups who use Hessian + tolerance
→ how can this be?
- Assuming sufficient observables to determine PDFs, then PDF uncertainties cannot depend on parametrization!

Non-Gaussian likelihood

Incompatible data sets

- Rigorous (Bayesian) way to address incompatible data sets is to use generalization of Gaussian likelihood
 - joint vs. disjoint distributions
 - empirical Bayes
 - hierarchical Bayes
 - others, used in different fields

Disjoint distributions

- Instead of using total likelihood that is a product (“and”) of individual likelihoods, *e.g.* for simple example of two measurements

$$\mathcal{L}(m_1 m_2 | m; \delta m_1 \delta m_2) = \mathcal{L}(m_1 | m; \delta m_1) \times \mathcal{L}(m_2 | m; \delta m_2)$$

use instead sum (“or”) of individual likelihoods

$$\mathcal{L}(m_1 m_2 | m; \delta m_1 \delta m_2) = \frac{1}{2} \left[\mathcal{L}(m_1 | m; \delta m_1) + \mathcal{L}(m_2 | m; \delta m_2) \right]$$

→ gives rather different expectation value and variance

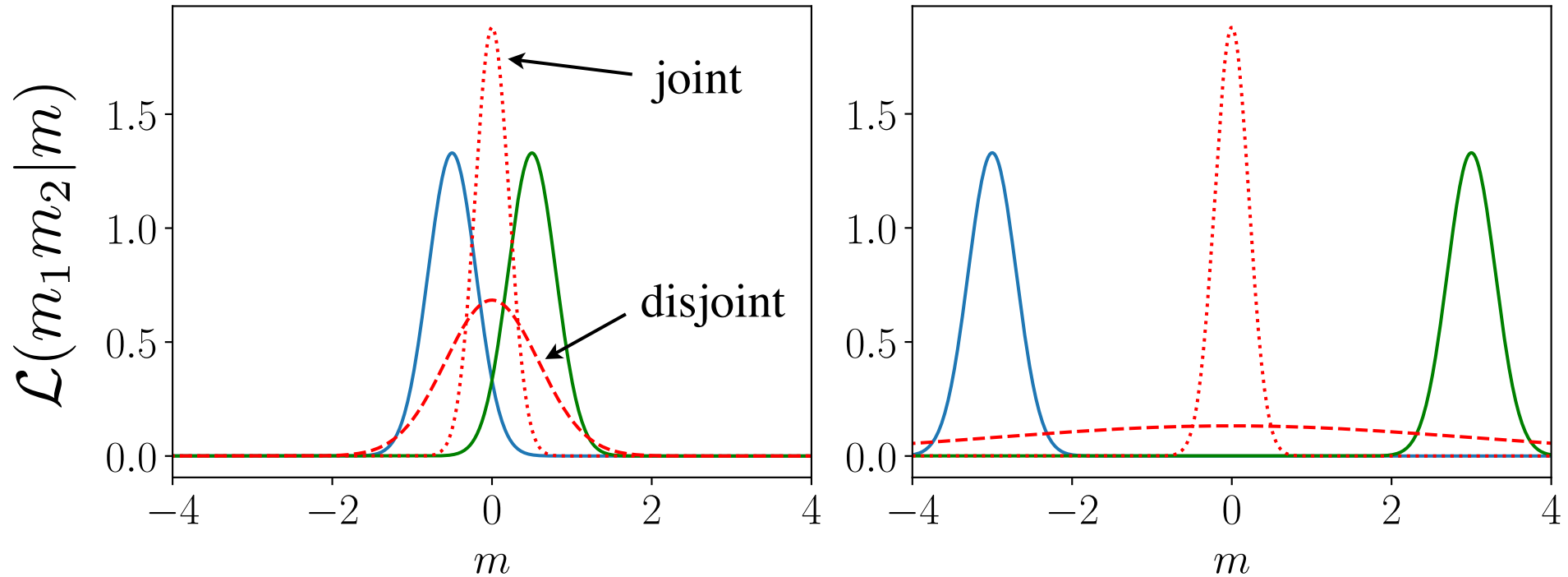
$$E[m] = \frac{1}{2} (m_1 + m_2)$$

$$V[m] = \frac{1}{2} (\delta m_1^2 + \delta m_2^2) + \left(\frac{m_1 - m_2}{2} \right)^2$$

depends on
separation!

Disjoint distributions

■ Symmetric uncertainties $\delta m_1 = \delta m_2$

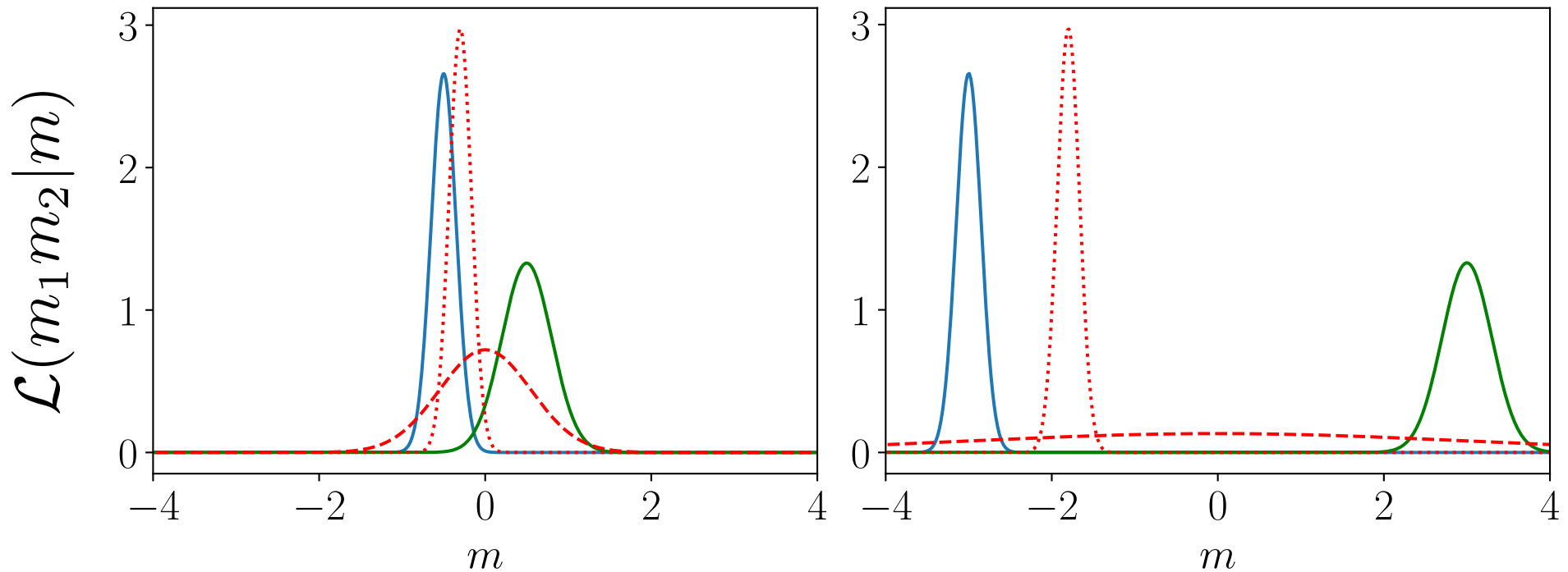


disjoint:
$$V[m] = \frac{1}{2}(\delta m_1^2 + \delta m_2^2) + \left(\frac{m_1 - m_2}{2} \right)^2$$

joint:
$$V[m] = \frac{\delta m_1^2 \delta m_2^2}{\delta m_1^2 + \delta m_2^2}$$

Disjoint distributions

■ Asymmetric uncertainties $\delta m_1 \neq \delta m_2$



→ disjoint likelihood gives broader overall uncertainty, overlapping individual (discrepant) data

Empirical Bayes

- Shortcoming of conventional Bayesian — still assume prior distribution follows specific form (*e.g.* Gaussian)
- Extend approach to more fully represent prior uncertainties, with final uncertainties that do not depend on initial choices
- In generalized approach, data uncertainties modified by distortion parameters, whose probability distributions given in terms of “hyperparameters” (or “nuisance parameters”)
- Hyperparameters determined from data
 - give posteriors for both PDF and hyperparameters

Empirical Bayes

- Standard mean and variance that characterize data

$$\theta = \mu + \sigma \longrightarrow f(\mu) + g(\sigma)$$

where $f(\mu), g(\sigma)$ are unknown functions that account for faulty measurements

- Simple choice is

$$(\mu, \sigma) \rightarrow (\zeta_1 \mu + \zeta_2, \zeta_3 \sigma)$$

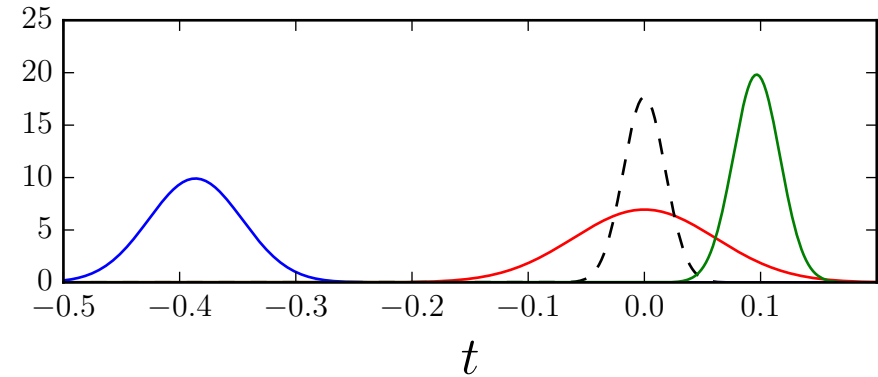
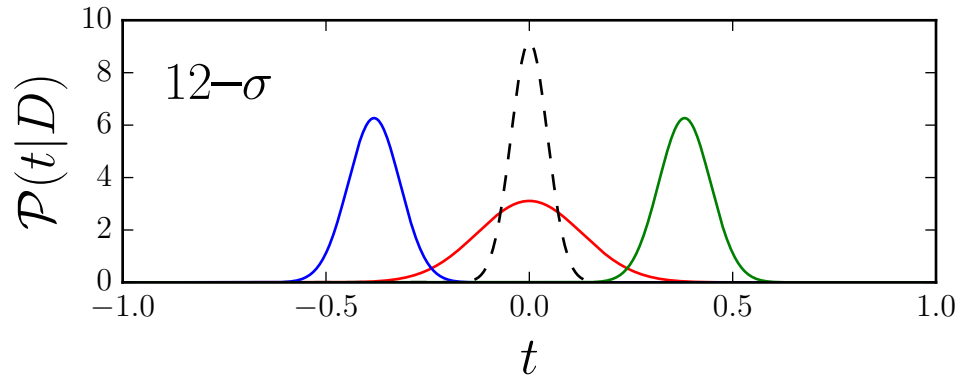
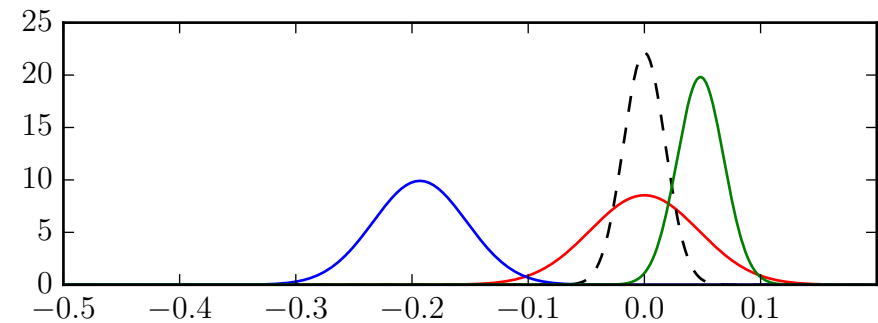
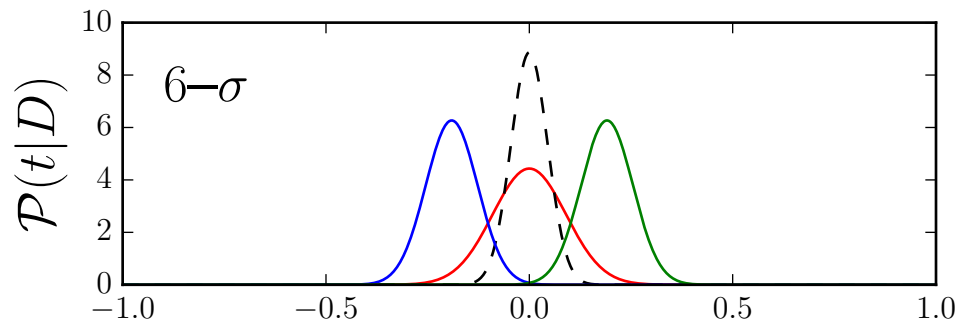
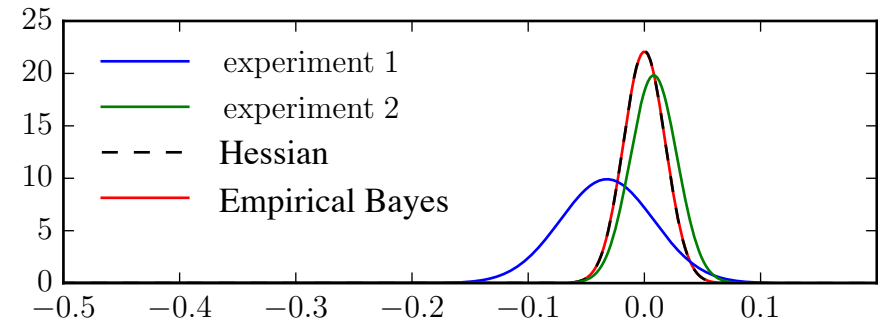
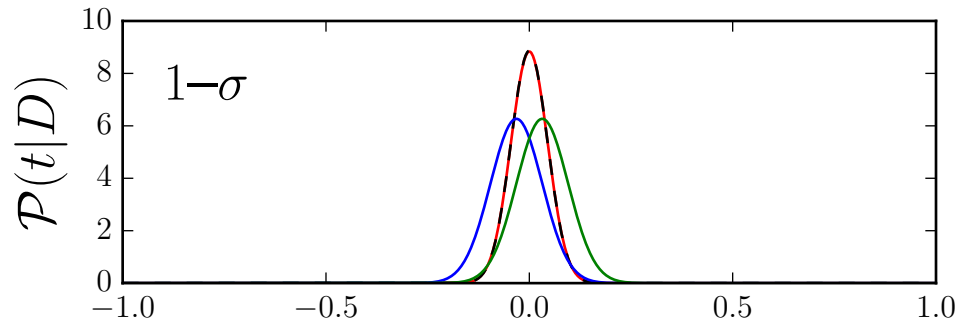
where $\zeta_{1,2,3}$ are distortion parameters, with prob. dists. described by hyperparameters $\phi_{1,2,3}$

- Likelihood function is then

$$\mathcal{L}(\text{data}|\vec{a}, \zeta_{1,2,3}) \sim \exp \left[-\frac{1}{2} \sum_i \left(\frac{d_i - f(\mu_i(\vec{a}, \zeta_{1,2}))}{g(\sigma, \zeta_3)} \right)^2 \right] \pi_1(\zeta_1|\phi_1) \pi_2(\zeta_2|\phi_2) \pi_3(\zeta_3|\phi_3)$$

Empirical Bayes

■ Simple example of EB for symmetric & asymmetric errors



Outlook

- New paradigm needed in global QCD analysis
 - simultaneous determination of collinear distributions (also TMDs) using Monte Carlo sampling of parameter space
- Treatment of discrepant data sets needs serious attention
 - Bayesian perspective has clear merits
- Necessary to benchmark MC extractions (not just NNPDF)
- Near-term future: “universal” QCD analysis of all observables sensitive to collinear (unpolarized & polarized) PDFs and FFs
- Longer-term: apply MC technology to global QCD analysis of transverse momentum dependent (TMD) PDFs and FFs