# PDF uncertainties. <br> What is the meaning of this? 

## Wally Melnitchouk

Jefferson Lab

## Outline

- Why are PDF uncertainties important to know?
- Why the need for a new global QCD analysis paradigm?
$\rightarrow$ Bayesian approach to fitting
$\longrightarrow$ single-fit (Hessian) vs. Monte Carlo approaches
- Incompatible data sets
$\rightarrow$ "tolerance" factors
■ Generalization to non-Gaussian likelihoods
$\rightarrow$ disjoint probabilities, empirical Bayes, ...
■ Outlook


## Why are PDF uncertainties important?

- In searches for new physics beyond the Standard Model a major source of uncertainty on limits/discoveries is from calculation of QCD backgrounds $\rightarrow$ PDF errors!
"The PDF and $\alpha_{s}$ uncertainties were calculated using the PDF4LHC prescription [39] with the MSTW2008 68\% CL NNLO [40, 41], CT10 NNLO [42, 43], and NNPDF2.3 5f FFN [44] PDF sets, and added in quadrature to the scale uncertainty."

Measurements of the charge asymmetry in top-quark pair production in the dilepton final state at $\sqrt{ } s=8$ TeV with the ATLAS detector PRD 94, 032006 (2016)
$\longrightarrow$ drives a large part of the global PDF community (esp. LHC)

- Limits understanding of nucleon structure
$\longrightarrow$ e.g. momentum and spin distributions of $d$ quarks at large $x$
$\longrightarrow$ motivation for several JLab12 experiments (MARATHON, BONuS, SoLID,...)


## $d / u$ ratio at large $x$

- Traditionally extracted from neutron / proton structure function ratio (where "neutron" $\sim$ deuteron - proton), but large nuclear uncertainties affect high- $x$ region



MARATHON Collaboration
Petratos, Katramatou, Gomez et al.

## $d / u$ ratio at large $x$

- Traditionally extracted from neutron / proton structure function ratio (where "neutron" ~ deuteron - proton), but large nuclear uncertainties affect high- $x$ region
$\rightarrow$ cannot discriminate between predictions for $d / u$ at $x \sim 1$


Owens, Accardi, WM (2013)

## $d / u$ ratio at large $x$

- More recently CJ15 analysis found significant reduction of PDF errors with inclusion of DØ W-asymmetry \& BONuS data



Accardi, Brady, WM, Owens, Sato (2016)
$\rightarrow$ extrapolated ratio at $x=1: d / u \rightarrow 0.09 \pm 0.03$
$\rightarrow$ note: errors are $90 \% \mathrm{CL}\left(\Delta \chi^{2}=2.7\right)$

## $d / u$ ratio at large $x$

- Different groups use different definitions of PDF uncertainties to take into account tensions between data sets
$\rightarrow$ multiply uncertainties by "tolerance" factor $T=\sqrt{\Delta \chi^{2}}$

... is this a meaningful comparison?


## $d / u$ ratio at large $x$

- Dependence on PDF parametrization
$\rightarrow$ recent analysis by AKP has tiny uncertainties, and $d / u \rightarrow 0$, which we (CJ) believe is simply parametrization bias!


Alekhin, Kulagin, Petti (2017)


* same functional form for $u \& d \sim(1-x)^{\beta}$
$\dagger$ more flexible form $d \rightarrow d+a x^{b} u$
... is there a more robust analysis?


## Need for new technology

- A major challenge has been to characterize PDF uncertainties - in a statistically meaningful way - in the presence of tensions among data sets
- Previous attempts sought to address tensions in data sets by introducing
$\rightarrow$ "tolerance" factors (artificially inflating PDF errors)
$\rightarrow$ "neural net" parametrization (instead of polynomial parametrization), together with MC techniques
- However, to address the problem in a more statistically rigorous way, one requires going beyond the standard $\chi^{2}$ minimization paradigm
$\rightarrow$ utilize modern techniques based on Bayesian statistics!


## Need for new technology

- In the near future, standard $\chi^{2}$ minimization techniques will be unsuitable - even in the absence of tensions e.g. for
$\rightarrow$ simultaneous analysis of collinear distributions (unpolarized \& polarized PDFs, fragmentation functions)
$\rightarrow$ new types of observables - TMDs or GPDs that will involve $>\mathcal{O}\left(10^{5}\right)$ data points, with $\mathcal{O}\left(10^{3}\right)$ parameters


## Need for new technology

- Typically PDF parametrizations are nonlinear functions of the PDF parameters, e.g.

$$
x f(x, \mu)=N x^{\alpha}(1-x)^{\beta} P(x)
$$

where $P$ is a polynomial e.g. $P(x)=1+\epsilon \sqrt{x}+\eta x$, or Chebyshev, neural net, ...
$\rightarrow$ have multiple local minima present in the $\chi^{2}$ function

- Robust parameter estimation that thoroughly scans over a realistic parameter space, including multiple local minima, is only possible using MC methods


## Bayesian approach to fitting

Nobuo Sato

main instigator

## Bayesian approach to fitting

- Analysis of data requires estimating expectation values $E$ and variances $V$ of "observables" $\mathcal{O}$ (= PDFs, FFs) which are functions of parameters $\vec{a}$

$$
\begin{aligned}
& E[\mathcal{O}]=\int d^{n} a \mathcal{P}(\vec{a} \mid \text { data }) \mathcal{O}(\vec{a}) \\
& V[\mathcal{O}]=\int d^{n} a \mathcal{P}(\vec{a} \mid \text { data })[\mathcal{O}(\vec{a})-E[\mathcal{O}]]^{2}
\end{aligned}
$$

"Bayesian master formulas"

- Using Bayes' theorem, probability distribution $\mathcal{P}$ given by

$$
\mathcal{P}(\vec{a} \mid \text { data })=\frac{1}{Z} \mathcal{L}(\text { data } \mid \vec{a}) \pi(\vec{a})
$$

in terms of the likelihood function $\mathcal{L}$

## Bayesian approach to fitting

- Likelihood function

$$
\mathcal{L}(\text { data } \mid \vec{a})=\exp \left(-\frac{1}{2} \chi^{2}(\vec{a})\right)
$$

is a Gaussian form in the data, with $\chi^{2}$ function

$$
\chi^{2}(\vec{a})=\sum_{i}\left(\frac{\operatorname{data}_{i}-\text { theory }_{i}(\vec{a})}{\delta(\text { data })}\right)^{2}
$$

with priors $\pi(\vec{a})$ and "evidence" $Z$

$$
Z=\int d^{n} a \mathcal{L}(\operatorname{data} \mid \vec{a}) \pi(\vec{a})
$$

$\rightarrow \quad Z$ tests if e.g. an $n$-parameter fit is statistically different from ( $n+1$ )-parameter fit

## Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:

Maximum Likelihood<br>Monte Carlo<br>( $\chi^{2}$ minimization)

## Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:


## Maximum Likelihood

( $\chi^{2}$ minimization)
$\longrightarrow$ maximize probability distribution $\mathcal{P}$ by minimizing $\chi^{2}$ for a set of best-fit parameters $\vec{a}_{0}$

$$
E[\vec{a}]=\vec{a}_{0}
$$

$\longrightarrow$ if $\mathcal{O}$ is $\approx$ linear in the parameters, and if probability is symmetric in all parameters

$$
E[\mathcal{O}(\vec{a})] \approx \mathcal{O}\left(\vec{a}_{0}\right)
$$

## Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:


## Maximum Likelihood

$$
\left(\chi^{2} \text { minimization }\right)
$$

$\longrightarrow$ variance computed by expanding $\mathcal{O}(\vec{a})$ about $\vec{a}_{0}$ $e . g$. in 1 dimension have "master formula"

$$
V[\mathcal{O}] \approx \frac{1}{4}[\mathcal{O}(a+\delta a)-\mathcal{O}(a-\delta a)]^{2}
$$

where

$$
\delta a^{2}=V[a]
$$

## Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:


## Maximum Likelihood

( $\chi^{2}$ minimization)
$\longrightarrow$ generalization to multiple dimensions via Hessian approach: find set of (orthogonal) contours in parameter space around $\vec{a}_{0}$ such that $\mathcal{L}$ along each contour is parametrized by statistically independent parameters - directions of contours given by eigenvectors $\hat{e}_{k}$ of Hessian matrix $H$, with elements

$$
H_{i j}=\left.\frac{1}{2} \frac{\partial^{2} \chi^{2}(\vec{a})}{\partial a_{i} \partial a_{j}}\right|_{\vec{a}=\vec{a}_{0}}
$$

and contours parametrized as $\Delta a^{(k)}=a^{(k)}-a_{0}=t_{k} \frac{\hat{e}_{k}}{\sqrt{v_{k}}}$,
with $v_{k}$ eigenvectors of $H$ with $v_{k}$ eigenvectors of $H$

## Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:

Maximum Likelihood
( $\chi^{2}$ minimization)
$\longrightarrow$ basic assumption: $\mathcal{P}$ factorizes along each eigendirection

$$
\mathcal{P}(\Delta a) \approx \prod_{k} \mathcal{P}_{k}\left(t_{k}\right)
$$

where

$$
\mathcal{P}_{k}\left(t_{k}\right)=\mathcal{N}_{k} \exp \left[-\frac{1}{2} \chi^{2}\left(a_{0}+t_{k} \frac{\hat{e}_{k}}{\sqrt{v_{k}}}\right)\right]
$$

note: in quadratic approximation for $\chi^{2}$, this becomes a normal distribution

## Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:


## Maximum Likelihood

$$
\left(\chi^{2} \text { minimization }\right)
$$

$\longrightarrow$ uncertainties on $\mathcal{O}$ along each eigendirection (assuming linear approximation)

$$
\left(\Delta \mathcal{O}_{k}\right)^{2} \approx \frac{1}{4}\left[\mathcal{O}\left(a_{0}+T_{k} \frac{\hat{e}_{k}}{\sqrt{v_{k}}}\right)-\mathcal{O}\left(a_{0}-T_{k} \frac{\hat{e}_{k}}{\sqrt{v_{k}}}\right)\right]^{2}
$$

where $T_{k}$ is finite step size in $t_{k}$, with total variance

$$
V[\mathcal{O}]=\sum_{k}\left(\Delta \mathcal{O}_{k}\right)^{2}
$$

## Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:


## Monte Carlo

$\rightarrow$ in practice, generally one has $E[\mathcal{O}(\vec{a})] \neq \mathcal{O}(E[\vec{a}])$ so the maximal likelihood method will sometimes fail
$\rightarrow$ Monte Carlo approach samples parameter space and assigns weights $w_{k}$ to each set of parameters $a_{k}$
$\rightarrow$ expectation value and variance are then weighted averages

$$
E[\mathcal{O}(\vec{a})]=\sum_{k} w_{k} \mathcal{O}\left(\vec{a}_{k}\right), \quad V[\mathcal{O}(\vec{a})]=\sum_{k} w_{k}\left(\mathcal{O}\left(\vec{a}_{k}\right)-E[\mathcal{O}]\right)^{2}
$$

## Bayesian approach to fitting

- Two methods generally used for computing Bayesian master formulas:


## Maximum Likelihood <br> ( $\chi^{2}$ minimization)

O fast

- assumes Gaussianity

O no guarantee that global minimum has been found

O errors only characterize local geometry of $\chi^{2}$ function

## Monte Carlo

O slow
O does not rely on
Gaussian assumptions
o includes all possible solutions

O accurate

## Incompatible data sets

N. Sato, M. Albright, WM, H. Prosper, M. White (2017)
A.Accardi, E. Nocera, N. Sato, WM (2018)

## Incompatible data sets

- Incompatible data sets can arise because of errors in determining central values, or underestimation of systematic experimental uncertainties
$\rightarrow$ requires some sort of modification to standard statistics
- Modify the master formula by introducing a "tolerance" factor $T$

$$
V[\mathcal{O}] \rightarrow T^{2} V[\mathcal{O}]
$$

e.g. for one dimension

$$
V[\mathcal{O}]=\frac{T^{2}}{4}[\mathcal{O}(a+\delta a)-\mathcal{O}(a-\delta a)]^{2}
$$

$\rightarrow$ effectively modifies the likelihood function

## Incompatible data sets

■ Simple example: consider observable $m$, and two measurements

$$
\left(m_{1}, \delta m_{1}\right), \quad\left(m_{2}, \delta m_{2}\right)
$$

$\rightarrow$ compute exactly the $\chi^{2}$ function

$$
\chi^{2}=\left(\frac{m-m_{1}}{\delta m_{1}}\right)^{2}+\left(\frac{m-m_{2}}{\delta m_{2}}\right)^{2}
$$

and, from Bayesian master formula, the mean value

$$
E[m]=\frac{m_{1} \delta m_{2}^{2}+m_{2} \delta m_{1}^{2}}{\delta m_{1}^{2}+\delta m_{2}^{2}}
$$

and variance

$$
V[m]=H^{-1}=\frac{\delta m_{1}^{2} \delta m_{2}^{2}}{\delta m_{1}^{2}+\delta m_{2}^{2}} \leadsto \begin{array}{r}
\text { does not } \\
\text { depend on } \\
m_{1}-m_{2}!
\end{array}
$$

## Incompatible data sets

■ Simple example: consider observable $m$, and two measurements

$$
\left(m_{1}, \delta m_{1}\right), \quad\left(m_{2}, \delta m_{2}\right)
$$



$\longrightarrow$ total uncertainty remains independent of degree of (in)compatibility of data
$\rightarrow$ Gaussian likelihood gives unrealistic representation of true uncertainty

## Incompatible data sets

## $\square$ Realistic example: recent CJ (CTEQ-JLab) global PDF analysis






$\longrightarrow$ data sets compatible along this e-direction
$\longrightarrow 24$ parameters, 33 data sets

## Incompatible data sets

$\square$ Realistic example: recent CJ (CTEQ-JLab) global PDF analysis


$\longrightarrow 24$ parameters, 33 data sets
$\longrightarrow$ data sets not compatible along this e-direction


| (0) aluv | (12) a2du |
| :---: | :---: |
| (1) a2uv | (13) a 4 du |
| (2) a4uv | (14) a 1 g |
| (3) a1dv | (15) a 2 g |
| (4) a2dv | (16) a3g |
| (5) a3dv | (17) a4g |
| (6) a4dv | (18) a6dv |
| (7) a0ud | (19) off1 |
| (8) a1ud | (20) off2 |
| (9) a2ud | (21) ht1 |
| (10) a4ud | (22) ht2 |
| (11) a1du | (23) ht3 |


|  | (0) TOTAL |  | (17) e866p |
| :---: | :---: | :---: | :---: |
|  | (1) HerF2pCut |  | (18) H2 CC |
|  | (2) slac |  | ) dorun2 |
|  | (3) doLasy 13 | - | (20) d0 gamj |
|  | (4) e866pd06xf | - | (21) CDFrun2jet |
|  | (5) BNS F2nd |  | (22) d0 gamjet3 |
|  | (6) NmcRatCor |  | (23) d0 gamjet2 |
|  | (7) slac d |  | (24) d0 gamjet4 |
|  | (8) D0 Z |  | (25) j100106F2d |
|  | (9) H2 NC ep 3 |  | (26) HerF2dCut |
|  | (10) H2 NC ep 2 | - | (27) BcdF2dCo |
|  | (11) H2 NC ep 1 | - | (28) CDF Z |
|  | (12) H2 NC ep 4 |  | (29) Do Wasy |
|  | (13) CDF Wasy |  | (30) H2 NC em |
|  | (14) H2 CC ep | - | (31) j100106F2p |
|  | (15) cdfLasy05 | - | (32) d0Lasy e15 |
|  | (16) NmcF2pCor |  | (33) BcdF2pCor |

## Incompatible data sets

$\square$ Realistic example: recent CJ (CTEQ-JLab) global PDF analysis


$\rightarrow 24$ parameters,
33 data sets
$\longrightarrow$ data sets not compatible along this e-direction
$\longrightarrow$ standard Gaussian likelihood incapable of accounting for underestimated individual errors (leading to incompatible data sets) - not designed for such scenarios!

## Incompatible data sets

- CTEQ tolerance criteria

- for each experiment, find minimum $\chi^{2}$ along given e-direction
- from $\chi^{2}$ distribution determine $90 \% \mathrm{CL}$ for each experiment
- along each side of e-direction, determine maximum range $d_{k}^{ \pm}$ allowed by the most constraining experiment
- $T$ computed by averaging over all $d_{k}^{ \pm}$(typically $T \sim 5-10$ )


## Incompatible data sets

- CTEQ tolerance criteria

$\square$ This approach is not consistent with Gaussian likelihood
$\longrightarrow$ no clear Bayesian interpretation of uncertainties (ultimately, a prescription...)

To summarize standard maximum likelihood method...

- Gradient search (in parameter space) depends how "good" the starting point is
$\rightarrow$ for $\sim 30$ parameters trying different starting points is impractical, if do not have some information about shape
- Common to free parameters initially, then freeze those not sensitive to data ( $\chi^{2}$ flat locally)
$\rightarrow$ introduces bias, does not guarantee that flat $\chi^{2}$ globally
- Cannot guarantee solution is unique
- Error propagation characterized by quadratic $\chi^{2}$ near minimum $\longrightarrow$ no guarantee this is quadratic globally (e.g. Student $t$-distribution?)
- Introduction of tolerance modifies Gaussian statistics


## Monte Carlo methods

## Monte Carlo

ㅁ Designed to faithfully compute Bayesian master formulas
$\square$ Do not assume a single minimum, include all possible solutions (with appropriate weightings)
$\square$ Do not assume likelihood is Gaussian in parameters
$\square$ Allows likelihood analysis to be extended to address tensions among data sets via Bayesian inference
$\square$ More computationally demanding compared with Hessian method

## Monte Carlo

$\square$ First group to use MC for global PDF analysis was NNPDF, using neural network to parametrize $P(x)$ in

Forte et al. (2002)

$$
f(x)=N x^{\alpha}(1-x)^{\beta} P(x)
$$

$-\alpha, \beta$ are fitted "preprocessing coefficients"
$\square$ Iterative Monte Carlo (IMC), developed by JAM Collaboration, variant of NNPDF, tailored to non-neutral net parametrizations

- Markov Chain MC (MCMC) / Hybid MC (HMC) - recent "proof of principle" analysis, ideas from lattice QCD

Gbedo, Mangin-Brinet (2017)
$\square$ Nested sampling (NS) - computes integrals in Bayesian master formulas (for $E, V, Z$ ) explicitly

Skilling (2004)

## Iterative Monte Carlo (IMC)

ㅁ Use traditional functional form for input distribution shape, but sample significantly larger parameter space than possible in single-fit analyses

```
Iterative Monte Carlo (IMC)
```


$\rightarrow$ no assumptions for exponents

$\rightarrow$ cross-validation to avoid overfitting
$\rightarrow$ iterate until convergence criteria satisfied

## Iterative Monte Carlo (IMC)

- e.g. of convergence (for fragmentation functions) in IMC


























## Nested Sampling

ㅁ Basic idea: transform $n$-dimensional integral to 1-D integral

$$
Z=\int d^{n} a \mathcal{L}(\text { data } \mid \vec{a}) \pi(\vec{a})=\int_{0}^{1} d X \mathcal{L}(X)
$$

where prior volume $d X=\pi(\vec{a}) d^{n} a$

such that $0<\cdots<X_{2}<X_{1}<X_{0}=1$

Feroz et al.
arXiv:1306.2144 [astro-ph]

## Nested Sampling

- Approximate evidence by a weighted sum

$$
Z \approx \sum_{i} \mathcal{L}_{i} w_{i} \quad \text { with weights } w_{i}=\frac{1}{2}\left(X_{i-1}-X_{i+1}\right)
$$

- Algorithm:
$\rightarrow$ randomly select samples from full prior s.t. initial volume $X_{0}=1$
$\rightarrow$ for each iteration, remove point with lowest $\mathcal{L}_{i}$, replacing it with point from prior with constraint that its $\mathcal{L}>\mathcal{L}_{i}$
$\rightarrow$ repeat until entire prior volume has been traversed
- can be parallelized
- performs better than VEGAS for large dimensions

O increasingly used in fields outside of (nuclear) analysis

## Nested Sampling

- Recent application in global analysis of transversity TMD PDF (SIDIS data + lattice QCD constraint on isovector moment)



Lin, WM, Prokudin, Sato, Shows (PRL, 2018)
$\rightarrow$ distributions do not look very Gaussian!
$\longrightarrow$ MC analysis gives $\delta u=0.3 \pm 0.2, \delta d=-0.7 \pm 0.2 \rightarrow g_{T}=1.0 \pm 0.1$
$\rightarrow$ maximum likelihood analysis would have given $g_{T} \approx 0.5$

## Nested Sampling

- Most recently applied to global analysis of pion PDFs
( $\pi A$ Drell-Yan data + leading neutron production at HERA)

P. Barry, N. Sato, WM, C.-R.Ji (2018)
$\rightarrow$ first constraints on sea quark PDFs in the pion


## MC Error Analysis

$\square$ Assuming a single minimum, a Hessian or MC analysis must give same results, if using same likelihood function
$\rightarrow$ analysis of pseudodata, generated using Gaussian distribution





## MC Error Analysis

$\square$ Assuming a single minimum, a Hessian or MC analysis must give same results, if using same likelihood function
$\rightarrow$ also for discrepant data


$\rightarrow$ almost identical uncertainty bands for Hessian and for MC!

## MC Error Analysis

$\square$ Assuming a single minimum, a Hessian or MC analysis must give same results, if using same likelihood function

- Approaches that use Hessian + tolerance factor not consistent with Gaussian likelihood function
$\square$ NNPDF group claim that within their neural net MC methodology, no need for a tolerance factor, since uncertainties similar to other groups who use Hessian + tolerance
$\rightarrow$ how can this be? E.Nocera, A.Accarli, N. Sato, WM, work in progress
$\square$ Assuming sufficient observables to determine PDFs, then PDF uncertainties cannot depend on parametrization!


## Non-Gaussian likelihood

## Incompatible data sets

- Rigorous (Bayesian) way to address incompatible data sets is to use generalization of Gaussian likelihood
- joint vs. disjoint distributions
- empirical Bayes
- hierarchical Bayes
- others, used in different fields


## Disjoint distributions

- Instead of using total likelihood that is a product ("and") of individual likelihoods, e.g. for simple example of two measurements

$$
\mathcal{L}\left(m_{1} m_{2} \mid m ; \delta m_{1} \delta m_{2}\right)=\mathcal{L}\left(m_{1} \mid m ; \delta m_{1}\right) \times \mathcal{L}\left(m_{2} \mid m ; \delta m_{2}\right)
$$

use instead sum ("or") of individual likelihoods

$$
\mathcal{L}\left(m_{1} m_{2} \mid m ; \delta m_{1} \delta m_{2}\right)=\frac{1}{2}\left[\mathcal{L}\left(m_{1} \mid m ; \delta m_{1}\right)+\mathcal{L}\left(m_{2} \mid m ; \delta m_{2}\right)\right]
$$

$\rightarrow$ gives rather different expectation value and variance

$$
\begin{aligned}
& E[m]=\frac{1}{2}\left(m_{1}+m_{2}\right) \\
& V[m]=\frac{1}{2}\left(\delta m_{1}^{2}+\delta m_{2}^{2}\right)+\left(\frac{m_{1}-m_{2}}{2}\right)^{2}
\end{aligned}
$$

## Disjoint distributions

- Symmetric uncertainties $\delta m_{1}=\delta m_{2}$

disjoint: $\quad V[m]=\frac{1}{2}\left(\delta m_{1}^{2}+\delta m_{2}^{2}\right)+\left(\frac{m_{1}-m_{2}}{2}\right)^{2}$
joint: $\quad V[m]=\frac{\delta m_{1}^{2} \delta m_{2}^{2}}{\delta m_{1}^{2}+\delta m_{2}^{2}}$


## Disjoint distributions

- Asymmetric uncertainties $\delta m_{1} \neq \delta m_{2}$

$\rightarrow$ disjoint likelihood gives broader overall uncertainty, overlapping individual (discrepant) data


## Empirical Bayes

- Shortcoming of conventional Bayesian - still assume prior distribution follows specific form (e.g. Gaussian)
- Extend approach to more fully represent prior uncertainties, with final uncertainties that do not depend on initial choices
- In generalized approach, data uncertainties modified by distortion parameters, whose probability distributions given in terms of "hyperparameters" (or "nuisance parameters")
- Hyperparameters determined from data
$\rightarrow$ give posteriors for both PDF and hyperparameters


## Empirical Bayes

- Standard mean and variance that characterize data

$$
\theta=\mu+\sigma \quad \longrightarrow f(\mu)+g(\sigma)
$$

where $f(\mu), g(\sigma)$ are unknown functions that account for faulty measurements

- Simple choice is

$$
(\mu, \sigma) \rightarrow\left(\zeta_{1} \mu+\zeta_{2}, \zeta_{3} \sigma\right)
$$

where $\zeta_{1,2,3}$ are distortion parameters, with prob. dists. described by hyperparameters $\phi_{1,2,3}$

- Likelihood function is then

$$
\mathcal{L}\left(\text { data } \mid \vec{a}, \zeta_{1,2,3}\right) \sim \exp \left[-\frac{1}{2} \sum_{i}\left(\frac{d_{1}-f\left(\mu_{i}\left(\vec{a}, \zeta_{1,2}\right)\right)}{g\left(\sigma, \zeta_{3}\right)}\right)^{2}\right] \pi_{1}\left(\zeta_{1} \mid \phi_{1}\right) \pi_{2}\left(\zeta_{1} \mid \phi_{2}\right) \pi_{3}\left(\zeta_{1} \mid \phi_{3}\right)
$$

## Empirical Bayes

## - Simple example of EB for symmetric \& asymmetric errors







N. Sato (2017)

## Outlook

■ New approaches being developed for global QCD analysis - simultaneous determination of parton distributions using Monte Carlo sampling of parameter space
$\square$ Treatment of discrepant data sets needs serious attention - Bayesian perspective has clear merits

■ Near-term future: "universal" QCD analysis of all observables sensitive to collinear (unpolarized \& polarized) PDFs and FFs

- Longer-term: apply MC technology to global QCD analysis of transverse momentum dependent (TMD) PDFs and FFs



