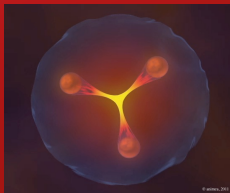


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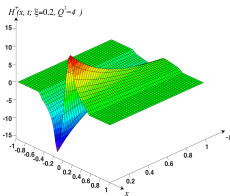
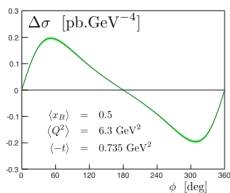
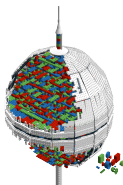


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Methods for Multidimensional Proton Imaging



CLAS Coll. Meeting 2015 | Hervé MOUTARDE

Oct. 21st, 2015

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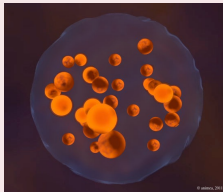
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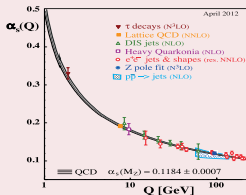
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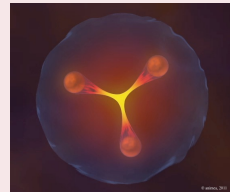
Perturbative QCD



Asymptotic freedom



Nonperturbative QCD



Perturbative AND nonperturbative QCD at work

- Define **universal** objects describing 3D nucleon structure:
Generalized Parton Distributions (GPD).
- Relate GPDs to measurements using **factorization**:
Virtual Compton Scattering (DVCS, TCS),
Deeply Virtual Meson production (DVMP).
- Get **experimental knowledge** of nucleon structure.

Methods for 3D Imaging

- Correlation of the **longitudinal momentum** and the **transverse position** of a parton in the nucleon.
- DVCS recognized as the cleanest channel to access GPDs.

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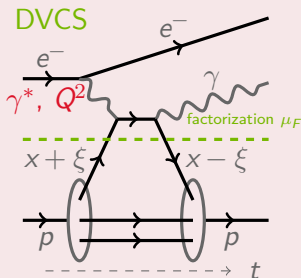
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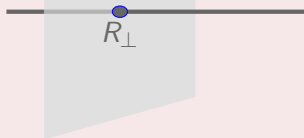
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Deeply Virtual Compton Scattering (DVCS)



Transverse center of momentum $R_\perp$

$$R_\perp = \sum_i x_i r_{\perp i}$$


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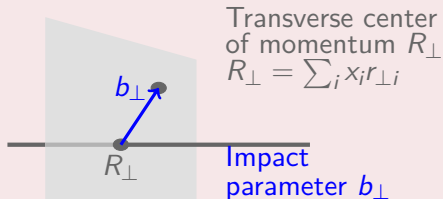
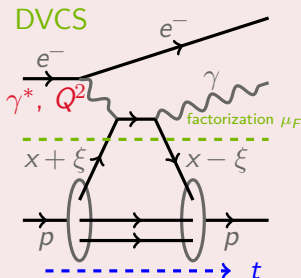
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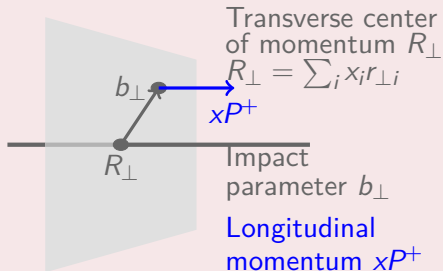
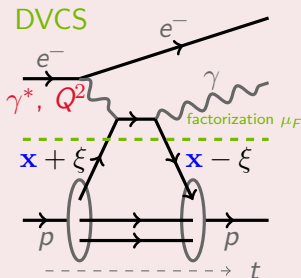
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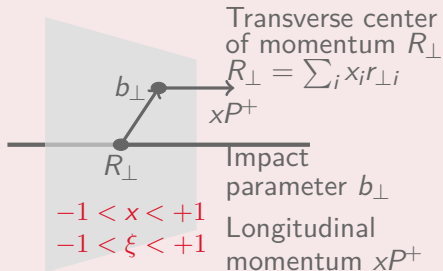
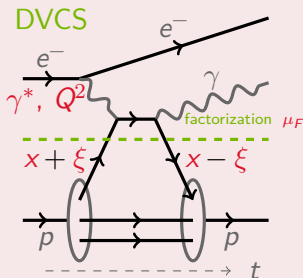
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Deeply Virtual Compton Scattering (DVCS)



- **24 GPDs** $F^i(x, \xi, t, \mu_F)$ for each parton type $i = g, u, d, \dots$ for leading and sub-leading twist.

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1 Measuring GPDs to image the nucleon.

2 Designing the tools.

3 Aggregating knowledge and know-how in the PARTONS software platform.

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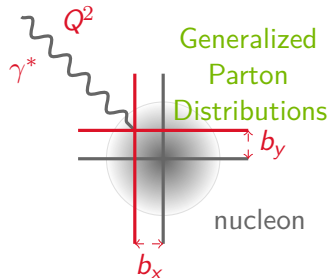
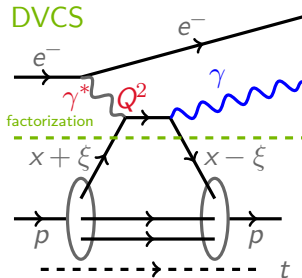
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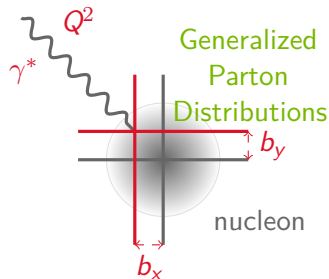
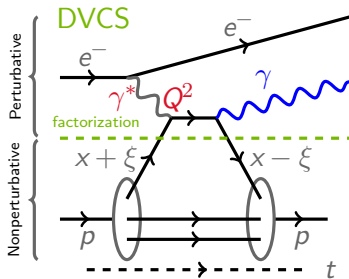
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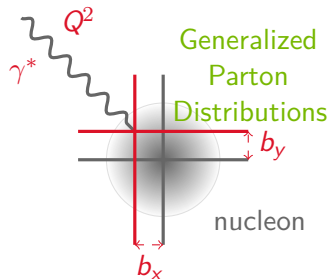
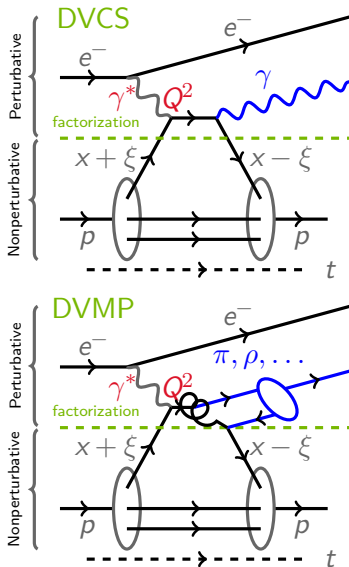
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Exclusive processes of current interest.

Factorization and universality.

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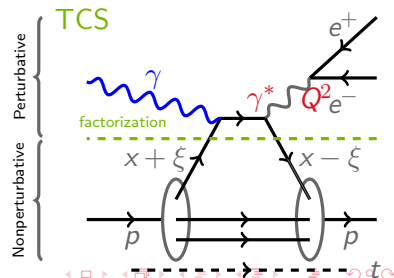
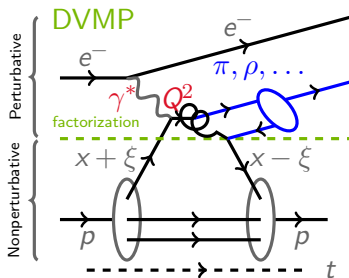
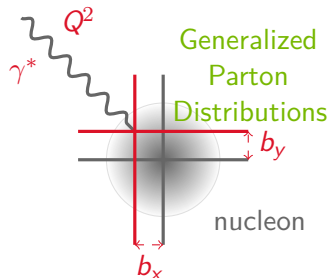
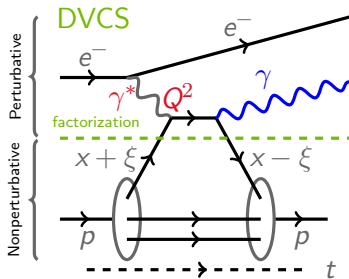
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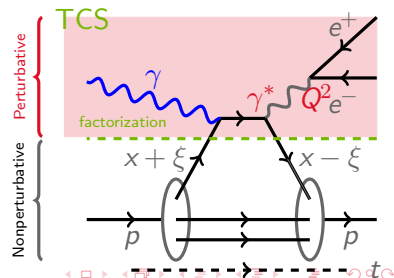
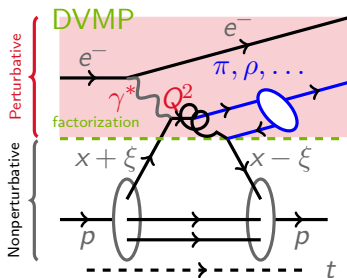
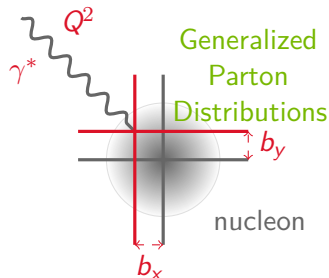
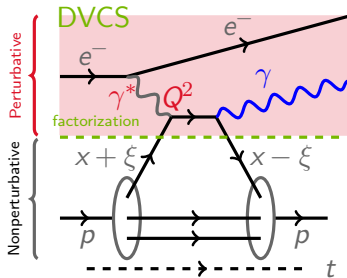
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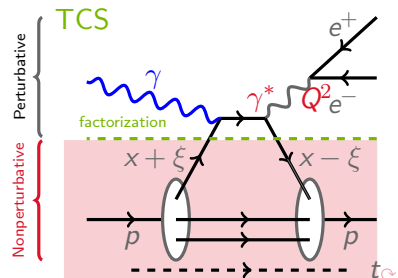
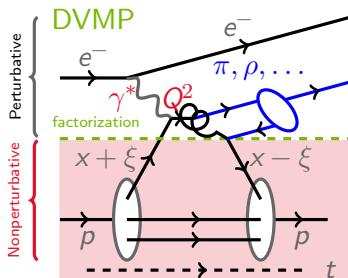
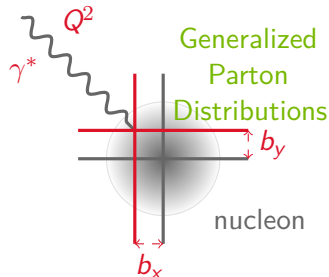
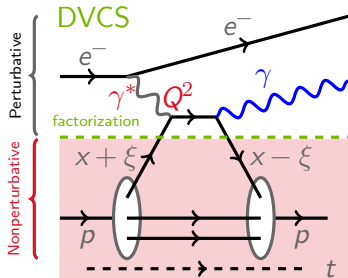
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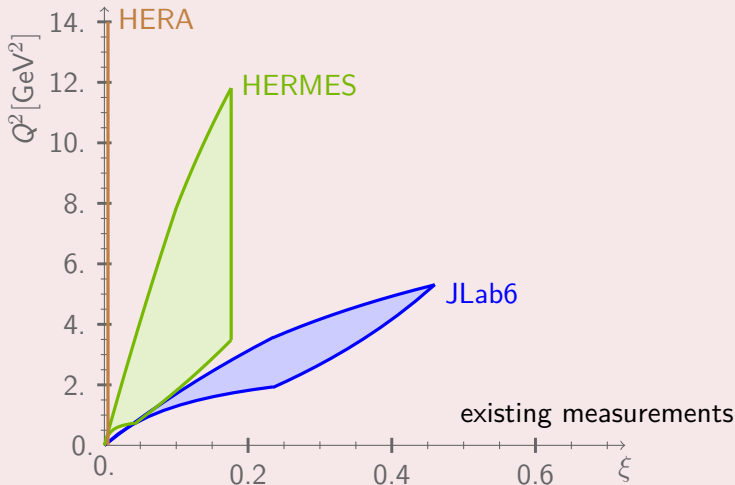
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Kinematic reach of existing or near-future DVCS measurements



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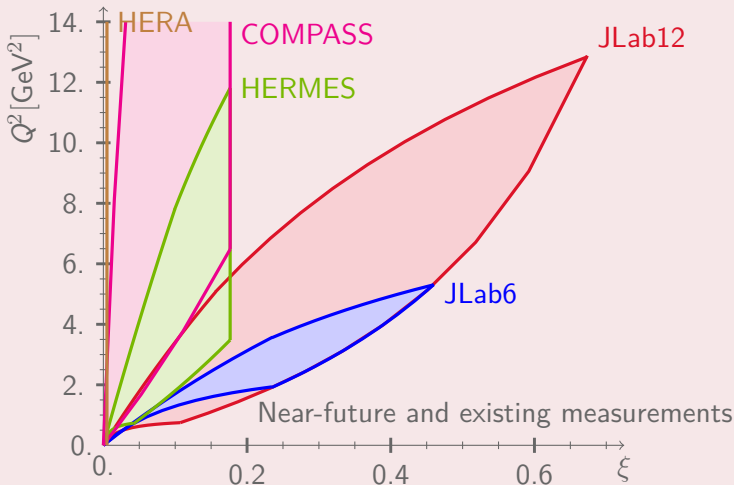
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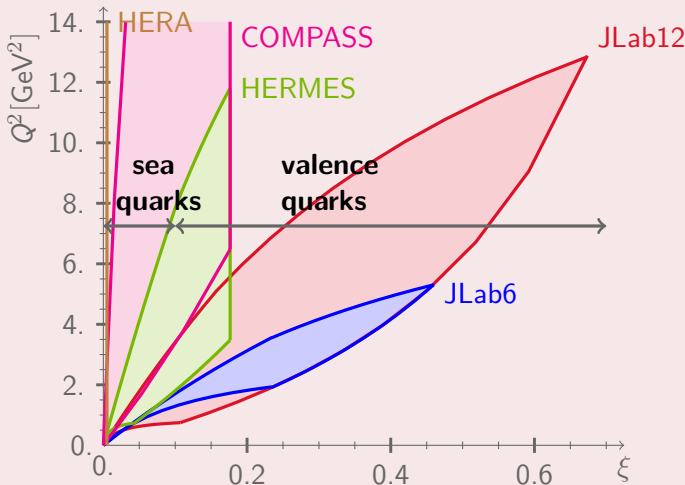
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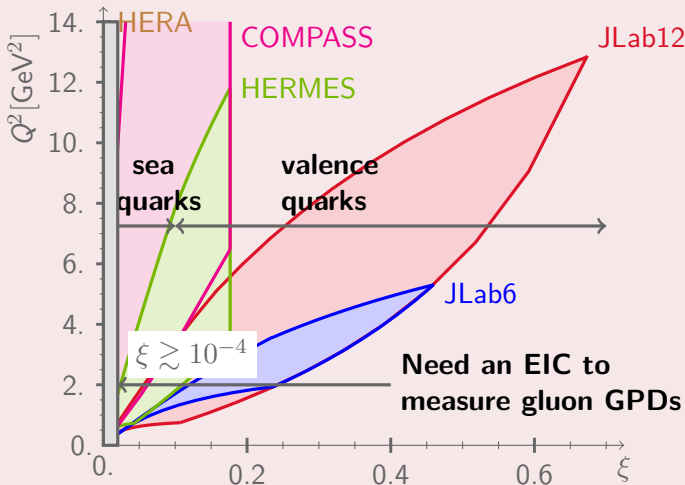
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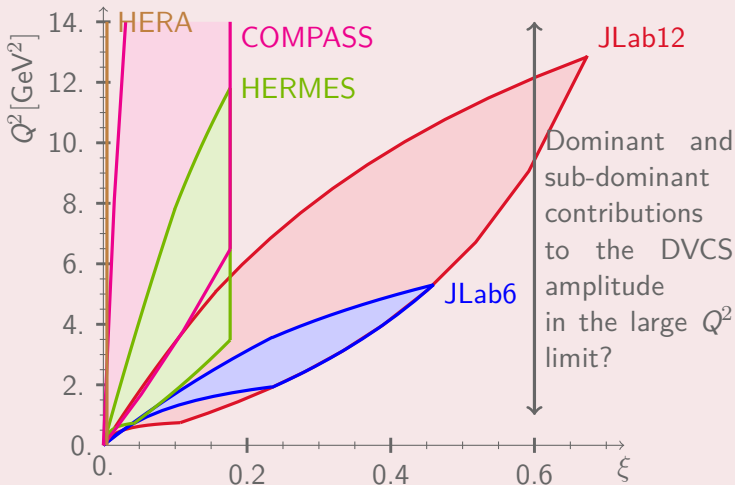
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1 Extract $H(x, \xi, t, \mu_F^{\text{ref}})$ from experimental data.

2 Extrapolate to vanishing skewness $H(x, 0, t, \mu_F^{\text{ref}})$.

3 Compute 2D Fourier transform in transverse plane:

$$H(x, b_{\perp}) = \int_0^{+\infty} \frac{d\Delta_{\perp}}{2\pi} \Delta_{\perp} J_0(b_{\perp} \Delta_{\perp}) H(x, 0, -\Delta_{\perp}^2)$$

4 Propagate uncertainties.

Case studies

Case studies

Lessons from past

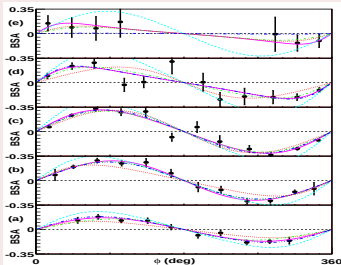
*"An expert is a man who has made all the mistakes
which can be made in a very narrow field."*

N. Bohr

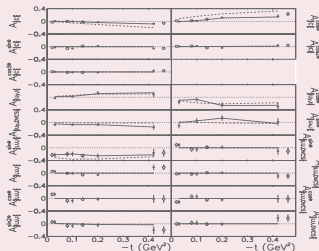
Handling multi-data sets.

What is the impact of one particular set of data?

Fits to CLAS and HERMES data



Moutarde, Phys. Rev. **D79**,
094021 (2009)



Guidal and Moutarde,
Eur. Phys. J. **A42**, 71 (2009)

- Two separate studies. Large code rewriting to mix both.
- Kinematic cuts not easy.
- Treat all observables **generically**, including **multi-channel** analysis.

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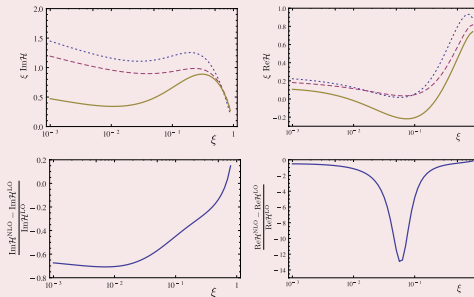
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$\mathcal{H}$ at LO and NLO ($t = -0.1 \text{ GeV}^2$, $Q^2 = \mu_F^2 = 4. \text{ GeV}^2$)



Moutarde *et al.*, Phys. Rev. **D87**, 054029 (2013)

- **Systematic** tests of perturbative QCD assumptions.
- **Wide kinematic range** (from JLab to EIC).
- **Accuracy** set by JLab 12 GeV expected statistical accuracy.
- **Modularity** for integration methods (time vs accuracy).

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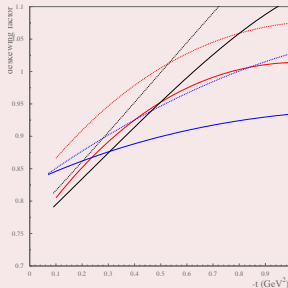
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Model-estimates of $H(\xi, 0, t)/H(\xi, \xi, t)$



- VGG
- dual Model
- GK
- Solid: $\xi \simeq 0.05$
- Dashed: $\xi \simeq 0.14$

Guidal *et al.*, Rept. Prog. Phys. **76**, 066202 (2013)

- **Systematic** computations with different GPD models.
- **Modularity** for GPD models. **Easy** integration.
- **No parameterization** relying on first principles only.
- **Relevant** for experiment design.

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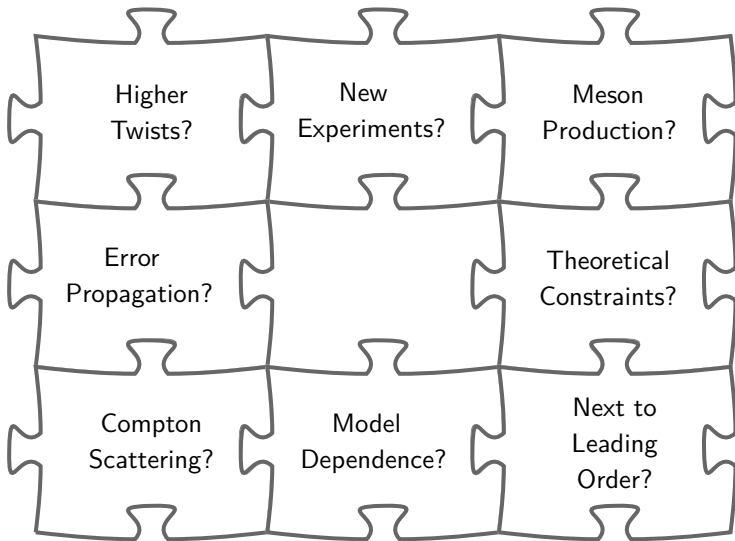
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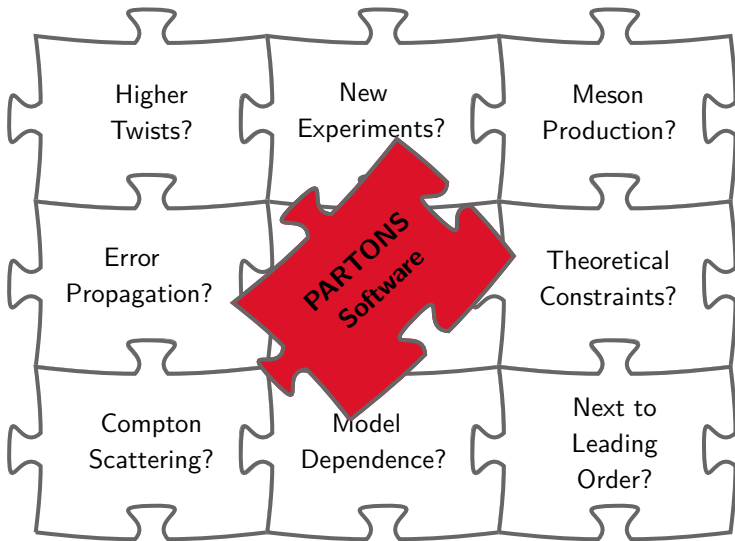
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PARtonic
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Experimental data and phenomenology

Full processes

Computation of amplitudes

Small distance contributions

First principles and fundamental parameters

Large distance contributions

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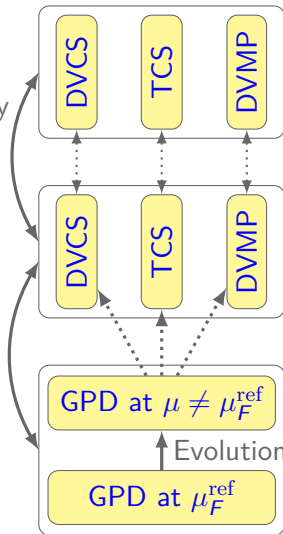
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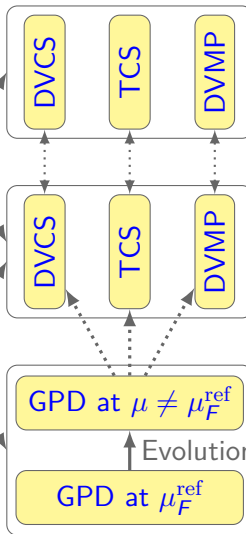
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Computation of amplitudes

First principles and fundamental parameters



- Many observables.
- Kinematic reach.

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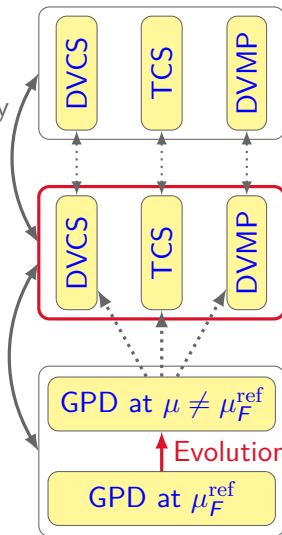
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Experimental data and phenomenology

Need for modularity

Computation of amplitudes

First principles and fundamental parameters



- Many observables.
- Kinematic reach.

- Perturbative approximations.
- Physical models.
- Fits.
- Numerical methods.
- Accuracy and speed.

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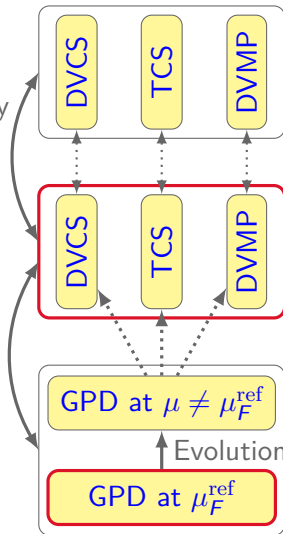
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- Many observables.
- Kinematic reach.

- Perturbative approximations.
- **Physical models.**
- Fits.
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Kinematic reach of DVCS
From observables to 3D images

Case studies

Data selection
Subdominant contributions
Model dependence
Challenges

PARTONS Project

Computing chain

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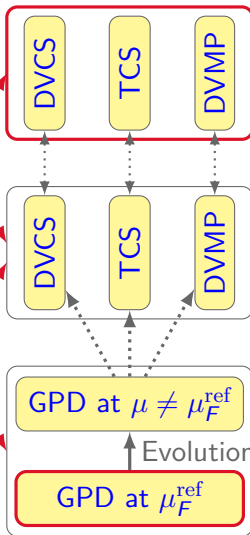
Conclusions

Experimental data and phenomenology

Need for modularity

Computation of amplitudes

First principles and fundamental parameters



- Many observables.
- Kinematic reach.

- Perturbative approximations.
- Physical models.
- Fits.
- Numerical methods.
- Accuracy and speed.

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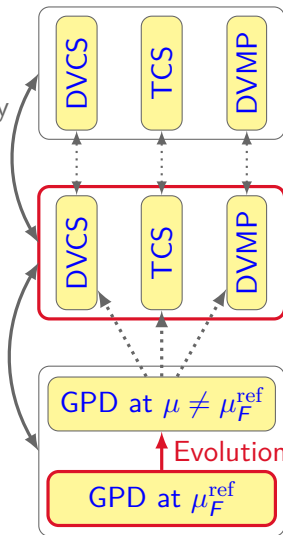
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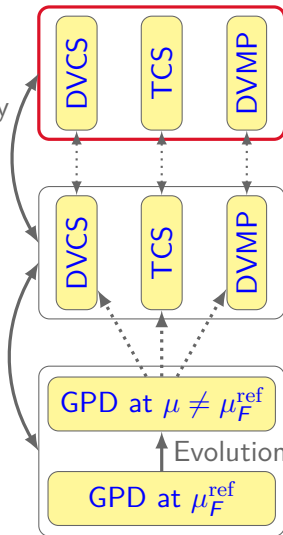
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- 3 stages:
 - 1 Design.
 - 2 Integration and validation.
 - 3 Production.
- Flexible software architecture.
 - B. Berthou *et al.*, *PARTONS: a computing platform for the phenomenology of Generalized Parton Distributions*
- 1 new physical development = 1 new module.
- *Aggregate* knowledge and know-how. *Do not* reinvent the wheel!
- What *can* be automated *will be* automated.
- Get ready for 12 GeV!

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```

_____ gpdExample() _____
1 // Lots of includes
2 #include <src/Partons.h>
3 ...
4
5 // Retrieve GPD service
6 GPDService* pGPDService = ServiceObjectRegistry::getGPDService();
7 // Load GPD module with the BaseModuleFactory
8 GPDModule* pGK11Model = ModuleObjectFactory::newGPDModule(
9 GK11Model::classId);
10 // Create a GPDKinematic(x, xi, t, MuF, MuR)
11 GPDKinematic gpdKinematic(0.1, xBToXi(0.001), -0.3, 8., 8.);
12 // Compute data and store results
13 GPDResult gpdResult = pGPDService->
    computeGPDModelRestrictedByGPDType(gpdKinematic, pGK11Model,
14 GPDType::ALL);
15 // Print results
16 std::cout << gpdResult.toString() << std::endl;
17
18 delete pGK11Model;
19 pGK11Model = 0;

```

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```

_____ computeOneGPD.xml _____
1 <?xml version="1.0" encoding="UTF-8" standalone="yes" ?>
2 <scenario id="01" date="" description="Example of computation of one GPD
   model (GK11) without evolution">
3     <!-- Select type of computation -->
4     <task service="GPDSservice" method="computeGPDModel" >
5         <!-- Specify kinematics -->
6         <GPDKinematic>
7             <param name="x" value="0.1" />
8             <param name="xi" value="1.00050025" />
9             <param name="t" value="-0.3" />
10            <param name="MuF2" value="8" />
11            <param name="MuR2" value="8" />
12        </GPDKinematic>
13        <!-- Choose GPD model and set parameters -->
14        <GPDModule>
15            <param name="id" value="GK11Model" />
16        </GPDModule>
17    </task>
18 </scenario>

```

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```

1  <?xml version="1.0" encoding="UTF-8" stand
2  <scenario id="01" date="" description="Exam
   _model_(GK11)_without_evolution">
3      <!-- Select type of computation -->
4      <task service="GPDSservice" method=
5          <!-- Specify kinematics -->
6          <GPDKinematic>
7              <param name="x" val
8              <param name="xi" va
9              <param name="t" val
10             <param name="MuF2"
11             <param name="MuR2"
12         </GPDKinematic>
13         <!-- Choose GPD model and
14         <GPDModule>
15             <param name="id" va
16         </GPDModule>
17     </task>
18 </scenario>

```

$$H^u = 0.822557$$

$$H^{u(+)} = 0.165636$$

$$H^{u(-)} = 1.47948$$

$$H^d = 0.421431$$

$$H^{d(+)} = 0.0805182$$

$$H^{d(-)} = 0.762344$$

$$H^s = 0.00883408$$

$$H^{s(+)} = 0.0176682$$

$$H^{s(-)} = 0$$

$$H^g = 0.385611$$

$$\text{and } E, \tilde{H}, \tilde{E}, \dots$$

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```

computeOneCFF.xml
1 <?xml version="1.0" encoding="UTF-8" standalone="yes" ?>
2 <scenario id="03" date="" description="Example of one
   convol_coeff_function_model (DVCS CFF) with GPD model (GK11)">
3   <task service="DVCSConvCoeffFunctionService" method="
   computeWithGPDModel"
4     <DVCSConvCoeffFunctionKinematic>
5       <param name="xi" value="0.5" />
6       <param name="t" value="-0.1346" />
7       <param name="Q2" value="1.5557" />
8       <param name="MuF2" value="4" />
9       <param name="MuR2" value="4" />
10    </DVCSConvCoeffFunctionKinematic>
11    <GPDMModule>
12      <param name="id" value="GK11Model" />
13    </GPDMModule>
14    <DVCSConvCoeffFunctionModule>
15      <param name="id" value="DVCS CFF Model" />
16      <param name="qcd_order_type" value="LO" />
17    </DVCSConvCoeffFunctionModule>
18  </task>
19 </scenario>

```

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```

computeOneCFF.xml
1 <?xml version="1.0" encoding="UTF-8" standalone="yes" ?>
2 <scenario id="03" date="" description="Example of computation of one
  convol coeff function model (DVCS CFF) with GPD model (GK11)">
3   <task service="DVCSConvolCoeffFunctionService" method="
    computeWithGPDModel"
4     <DVCSConvolCoeffFunctionKinematic>
5       <param name="xi" value="0.5" />
6       <param name="t" value="-0.1346" />
7       <param name="Q2" value="1.5557" />
8       <param name="MuF2" value="4" />
9       <param name="MuR2" value="4" />
10    </DVCSConvolCoeffFunctionKinematic>
11    <GPDMModule>
12      <param name="id" value="GK11Model" />
13    </GPDMModule>
14    <DVCSConvolCoeffFunction>
15      <param name="id" value="GK11Model" />
16      <param name="id" value="GK11Model" />
17    </DVCSConvolCoeffFunction>
18  </task>
19 </scenario>

```

$$\mathcal{H} = 1.47722 + 1.76698 i$$

$$\mathcal{E} = 0.12279 + 0.512312 i$$

$$\tilde{\mathcal{H}} = 1.54911 + 0.953728 i$$

$$\tilde{\mathcal{E}} = 18.8776 + 3.75275 i$$

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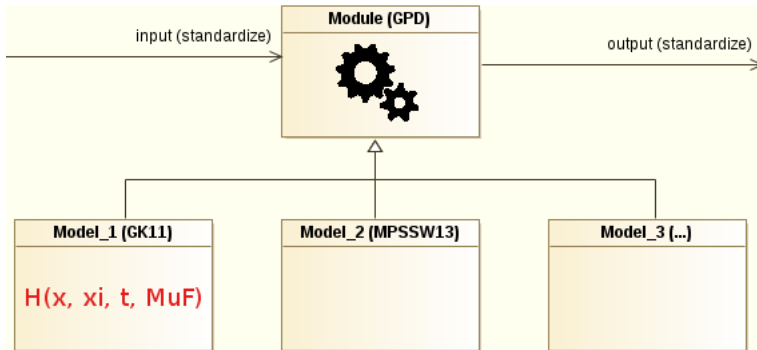
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- Steps of logic sequence in parent class.
- Model description and related mathematical methods in daughter class.

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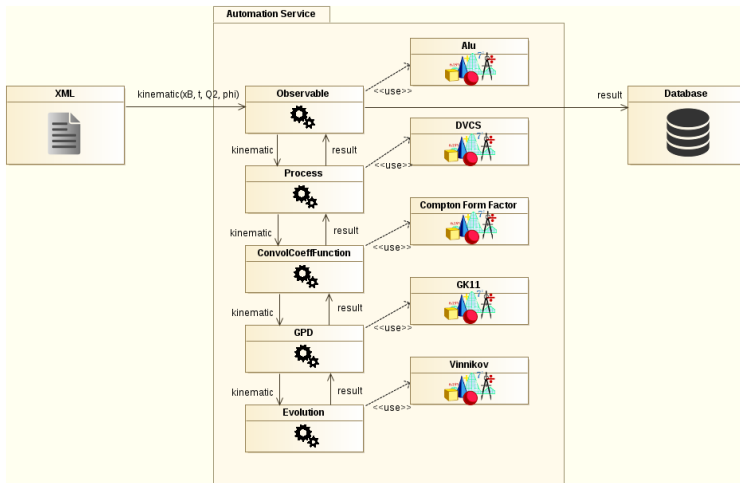
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Modularity and layer structure.

Modifying one layer does not affect the other layers.

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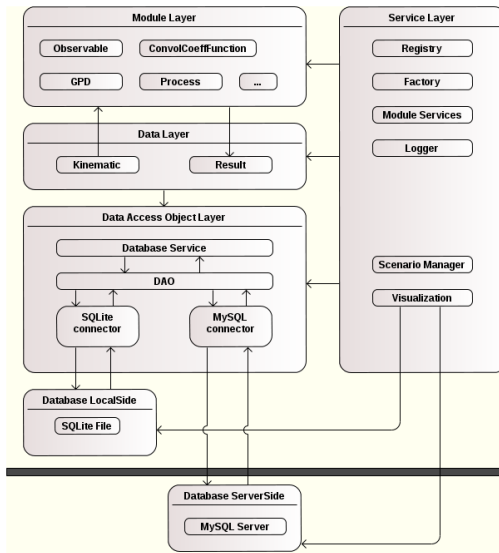
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Experimental data analysis Perturbative QCD
World data fits GPD modeling

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Conclusions

- PARTONS software Platform for GPD phenomenology near completion for DVCS channel.
- Designed to simplify:
 - Integration of new modules.
 - Systematic differential studies.
- Aim: up-to-date and validated GPD tools for:
 - Tests of pQCD assumptions.
 - Tests of model dependence.
 - Predictions of observables.
 - Experiment design.
 - Fits.
 - 3D nucleon imaging.
- Fitting test in 2016.

